Model Q45H/84

Hydrogen Peroxide Measurement System

Operation and Maintenance Manual

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PRODUCT WARRANTY

Analytical Technology, Inc. (Manufacturer) warrants to the Customer that if any part(s) of the Manufacturer's equipment proves to be defective in materials or workmanship within the earlier of 18 months of the date of shipment or 12 months of the date of start-up, such defective parts will be repaired or replaced free of charge. Inspection and repairs to products thought to be defective within the warranty period will be completed at the Manufacturer's facilities in Collegeville, PA. Products on which warranty repairs are required shall be shipped freight prepaid to the Manufacturer. The product(s) will be returned freight prepaid and allowed if it is determined by the manufacturer that the part(s) failed due to defective materials or workmanship.

This warranty does not cover consumable items, batteries, or wear items subject to periodic replacement including lamps and fuses.

Gas sensors carry a 12 months from date of shipment warranty and are subject to inspection for evidence of misuse, abuse, alteration, improper storage, or extended exposure to excessive gas concentrations. Should inspection indicate that sensors have failed due to any of the above, the warranty shall not apply.

The Manufacturer assumes no liability for consequential damages of any kind, and the buyer by acceptance of this equipment will assume all liability for the consequences of its use or misuse by the Customer, his employees, or others. A defect within the meaning of this warranty is any part of any piece of a Manufacturer's product which shall, when such part is capable of being renewed, repaired, or replaced, operate to condemn such piece of equipment.

This warranty is in lieu of all other warranties (including without limiting the generality of the foregoing warranties of merchantability and fitness for a particular purpose), guarantees, obligations or liabilities expressed or implied by the Manufacturer or its representatives and by statute or rule of law.

This warranty is void if the Manufacturer's product(s) has been subject to misuse or abuse, or has not been operated or stored in accordance with instructions, or if the serial number has been removed.

Analytical Technology, Inc. makes no other warranty expressed or implied except as stated above.

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Part 1 - Introduction

1.1   General

The Model Q45/84 is an on-line monitoring system designed for the continuous measurement of hydrogen peroxide (H_2O_2) concentration in water. The full scale operating range of the system may be selected by the user for 0-2.000 ppm, 0-20.00 ppm, or 0-200.0 ppm, and the sensing system will operate on water streams with temperatures ranging from 0 to 50°C. The Q45H/84 Monitor is engineered for applications in which H_2O_2 is applied to water for sterilization purposes.

The basic sensing element used in the monitor is a polarographic membraned sensor which measures hydrogen peroxide directly. Water simply flows past the sensor and directly to drain, with the flow rate and pressure across the sensor controlled by a constant head flow cell assembly. The sensor measurement does not alter the sample or add any chemicals to the sample stream, so the water flow can return to the system if desired.

Q45H/84 Monitors are available in three electronic versions, a loop-powered 2-wire transmitter, an AC powered monitor with integral alarm relays and dual 4-20 mA output capability, and a 12-24 VDC unit with dual output and relays

1.2   Standard System

The standard model Q45H/84 system includes three main components, the Q45/84 analyzer, a constant head flow cell, and an H_2O_2 sensor. A sealed flowcell is also available for applications where sample flowrate and pressure can be carefully controlled. Figure 1 shows a typical installation.

For connection of the sensor to the electronics, a 25' cable is supplied. An additional 100 feet of interconnect cable may be added using #07-0100 junction box. All required spare parts are also provided with the basic system, including spare membranes, electrolyte, o-rings, and any special hardware.
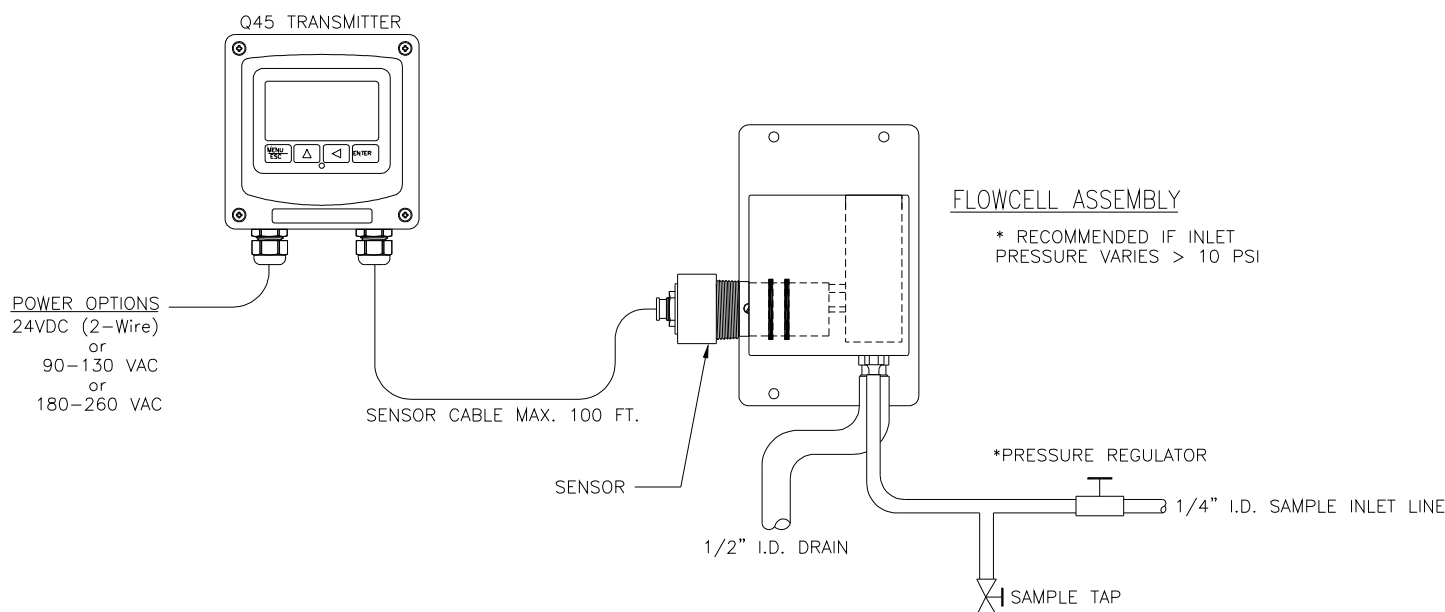
Figure 1 - Typical Monitoring System

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1.3   Features

- Standard Q45/84 electronic transmitters are designed to be a fully isolated, loop powered instruments for 2-wire DC applications.   Optional integral power supply card for 115/230 VAC operation or 12-24 VDC are available.

- High accuracy, high sensitivity system, measures from 0.1 ppb to 200.0 ppm through 4 internal automatic ranges. User ranges of 200.0 ppb, 2.000 ppm, 20.00 ppm, or 200.0 ppm.

- Output Hold, Output Simulate, Output Alarm, and Output Delay Functions. All forced changes in output condition include bumpless transfer to provide gradual return to on-line signal levels and to avoid system control shocks on both analog outputs.

- AC power option provides dual SPDT relay operation and one additional isolated analog output. Software settings for relay control include setpoint, deadband, phase, delay, and failsafe. Software controls automatically appear in menu list when hardware option card is plugged in and system power is applied.

- Selectable PID controller on main analog output. PID controller can operate with instrument configured as loop-power transmitter, or as one of the two outputs on the AC powered instrument. PID includes manual operation feature, and diagnostic "stuck-controller" timer feature for relay notification of control problems.

- Two analog outputs on the AC powered version may be configured to track H_2O_2 and temperature or both outputs can be set to correspond to H_2O_2 concentration. Both analog outputs can be individually programmed to fail to specific values.

- Selectable Output Fail Alarm feature on Relay B allows system diagnostic failures to be sent to external monitoring systems.

- Large, high contrast, custom LCD display with LED back light provides excellent readability in any light conditions. The secondary line of display utilizes 5x7 dot matrix characters for clear message display. Two of four measured parameters may be on the display simultaneously.

- Diagnostic messages provide a clear description of any problem with no confusing error codes to look up. Messages are also included for diagnosing calibration problems.

- Quick and easy one-point calibration method and sensor zero-cal. To provide high accuracy, all calibration methods include stability monitors that check temperature and main parameter stability before accepting data.

- High accuracy three-wire Pt100 temperature input. Temperature element can be user calibrated.

- Security lock feature to prevent unauthorized tampering with transmitter settings. All settings can be viewed while locked, but they cannot be changed.

- High reliability, microprocessor-based system with non-volatile memory back-up that utilizes no batteries. Low mass, surface mount PCB construction containing no adjustment potentiometers. All factory calibrations stored in non-volatile EEPROM.

1.4   Q45/84 System Specifications

(Common to all variations)

Displayed Parameters	Main input, 0.001 ppm to 200.0 ppm
	Sensor temperature, -10.0 to 55.0 °C (23 to 131 ºF)
	Sensor Current, 0.0–999.9 nA, 0.000 to 99.99 uA
	Loop current, 4.00 to 20.00 mA
	Sensor slope/offset
	Model number and software version
	PID Controller Status
Main Parameter Ranges	Manual selection of one of the following ranges,
	0.0 to 2.000 ppm
	0.00 to 20.00 ppm
	0.00 to 200.0 ppm
Display	0.75" (19.1 mm) high 4-digit main display with sign
	12-digit secondary display, 0.3" (7.6 mm) 5x7 dot matrix.
	Integral LED back-light for visibility in the dark.
Keypad	4-key membrane type with tactile feedback, polycarbonate with UV coating
Weight	DC transmitter configuration: 1 lb. (0.45 kg)
	Line powered unit: 1.5 lb. (0.68 kg)
Ambient Temperature	Analyzer Service, -20 to 60 °C (-4 to 140 ºF)
	Sensor Service, -5 to 55°C (23 to 131 °F)
	Storage, -5 to 70 °C (-22 to 158 ºF)
Ambient Humidity	0 to 95%, non-condensing.
EMI/RFI Influence	Designed to EN 61326-1
Output Isolation	600 V galvanic isolation
Filter	Adjustable 0-9.9 minutes additional damping to 90% step input
Temperature Input	Pt100 RTD with automatic compensation
Sensor	3-electrode polarographic membraned sensor for direct measurement of H_2O_2,
Sensor Materials	Noryl and PEEK

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Sensor Cable	25 ft. (7.5 meter) cable with 6-pin plug.
Max. Sensor-to-Analyzer Distance	100 feet (30.5 meters), with junction box
Flow Cell	Constant head overflow, clear cast acrylic, 7-30 GPH, 15 GPH recommended, inlet is ¼" hose barb at 1/8" MNPT, outlet is ½" hose barb at 3/8" MNPT

(NOT common to all variations)

Standard 2-Wire (Loop-powered) Transmitter:

Power	16-35 VDC (2-wire device)
Enclosure:	NEMA 4X, IP66, polycarbonate, stainless steel hardware, weatherproof and corrosion resistant, HWD: 4.4" (112 mm) x 4.4" (112 mm) x 3.5" (89 mm)
Mounting Options	Wall or pipe mount bracket standard. Bracket suitable for either 1.5" or 2" I.D. U-Bolts for pipe mounting.
Conduit Openings	Three PG-9 openings with gland seals
DC Cable Type	Belden twisted-pair, shielded, 22 gauge or larger
Insertion Loss	16 VDC

12-24 VC/115/230 VAC + Dual Relay Option:

Power	115/230 VAC ± 10%, 50/60 Hz, 10 VA max 12-24 VDC, 250 mA max.
Enclosure, AC Powered	NEMA 4X, IP66, polycarbonate, stainless steel hardware, weatherproof and corrosion resistant, HWD: 4.9" (124 mm) x 4.9" (124 mm) x 5.5" (139 mm)
Mounting Options	Wall or pipe mount bracket standard. Bracket suitable for either 1.5" or 2" I.D. U-Bolts for pipe mounting. Panel mount adapter optional.
Fuse	100 mA (120 VAC) or 50 mA (220 VAC) slow-blo on hot line, auto-reset secondary
Conduit Openings	Three ½" FNPT entries. Gland seals plus two ½" conduit adapters supplied but not installed.

Relays, Electromechanical:	Two SPDT, 6 amp @ 250 VAC, 5 amp @ 24 VDC contacts. Software selection for setpoint, phase, delay, deadband, hi-lo alarm, and failsafe. A-B indicators on main LCD.
Analog Outputs	Two 4-20 mA outputs. Output one programmable for PPM H_2O_2 or PID. Output 2 programmable for PPM H_2O_2, or Temperature. Max load 500 Ohms for each output. Outputs ground isolated and isolated from each other. Max. load for outputs on 12-24 VDC powered units is 400 ohms.

1.5   Q45 Performance Specifications

(Common to all variations)

Accuracy	0.5% of selected range or 0.02 PPM
Repeatability	0.3% of selected range or 0.01 PPM
Sensitivity	0.05% of selected range
Non-linearity	0.1% of selected range
Warm-up Time	3 seconds to rated performance (electronics only)
Supply Voltage Effects	± 0.05% span
Instrument Response Time	60 seconds to 90% of step input at lowest damping

Part 2 – Analyzer Mounting

2.1 General

All Q45 Series instruments offer maximum mounting flexibility. A bracket is included with each unit that allows mounting to walls or pipes. In all cases, choose a location that is readily accessible for calibrations. Also consider that it may be necessary to utilize a location where solutions can be used during the calibration process. To take full advantage of the high contrast display, mount the instrument in a location where the display can be viewed from various angles and long distances.

Locate the instrument in close proximity to the point of sensor installation - this will allow easy access during calibration. The sensor-to-instrument distance should not exceed 100 feet. To maximize signal-to-noise ratio however, work with the shortest sensor cable possible. The standard cable length of the H_2O_2 sensor is 25 feet.

Due to the flexibility of the instrument design, some of the mounting features change based on the configuration that was ordered. For example, the 2-wire transmitter version is different for the 115/230 VAC controller because the rear of the enclosure is much deeper when the AC powered unit is used. In addition, the AC powered unit has an integrated panel mount flange requiring a single cutout for flush mounting.

FRONT VIEW

BACK VIEW

SIDE VIEW

BOTTOM VIEW
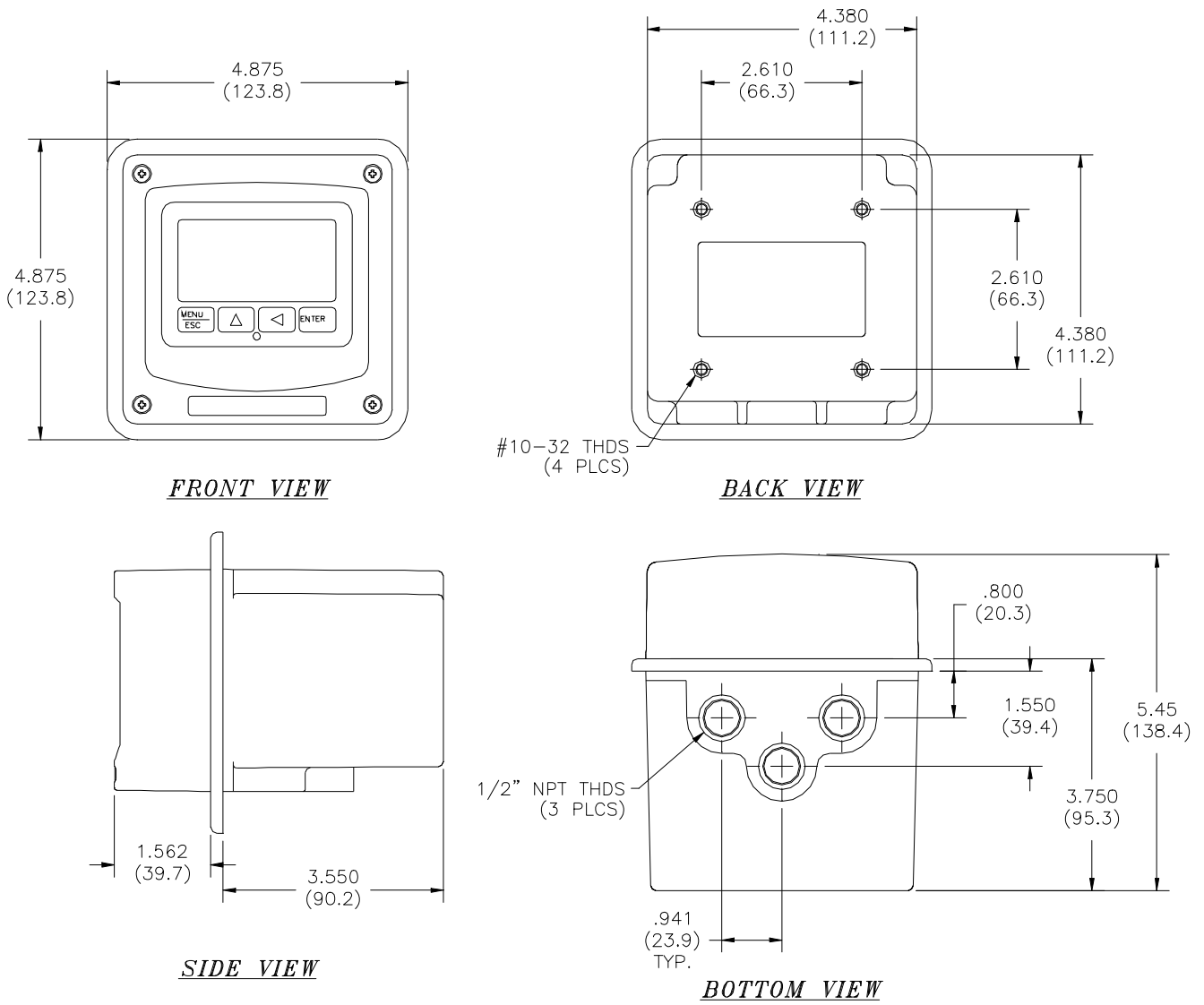
Figure 2 - Q45 Enclosure Dimensions, AC/DC Powered Units

FRONT VIEW

4.38
(111.2)

4.38
(111.2)

BACK VIEW

2.61
(66.3)

2.61
(66.3)

#10-32 UNF
(4 PLACES)

SIDE VIEW

1.68
(42.7)

3.45
(87.6)

BOTTOM VIEW

1" NPT

.82
(20.8)

1.23
(31.2)

1.23
(31.2)

PG-9 PORT
(2 PLACES)
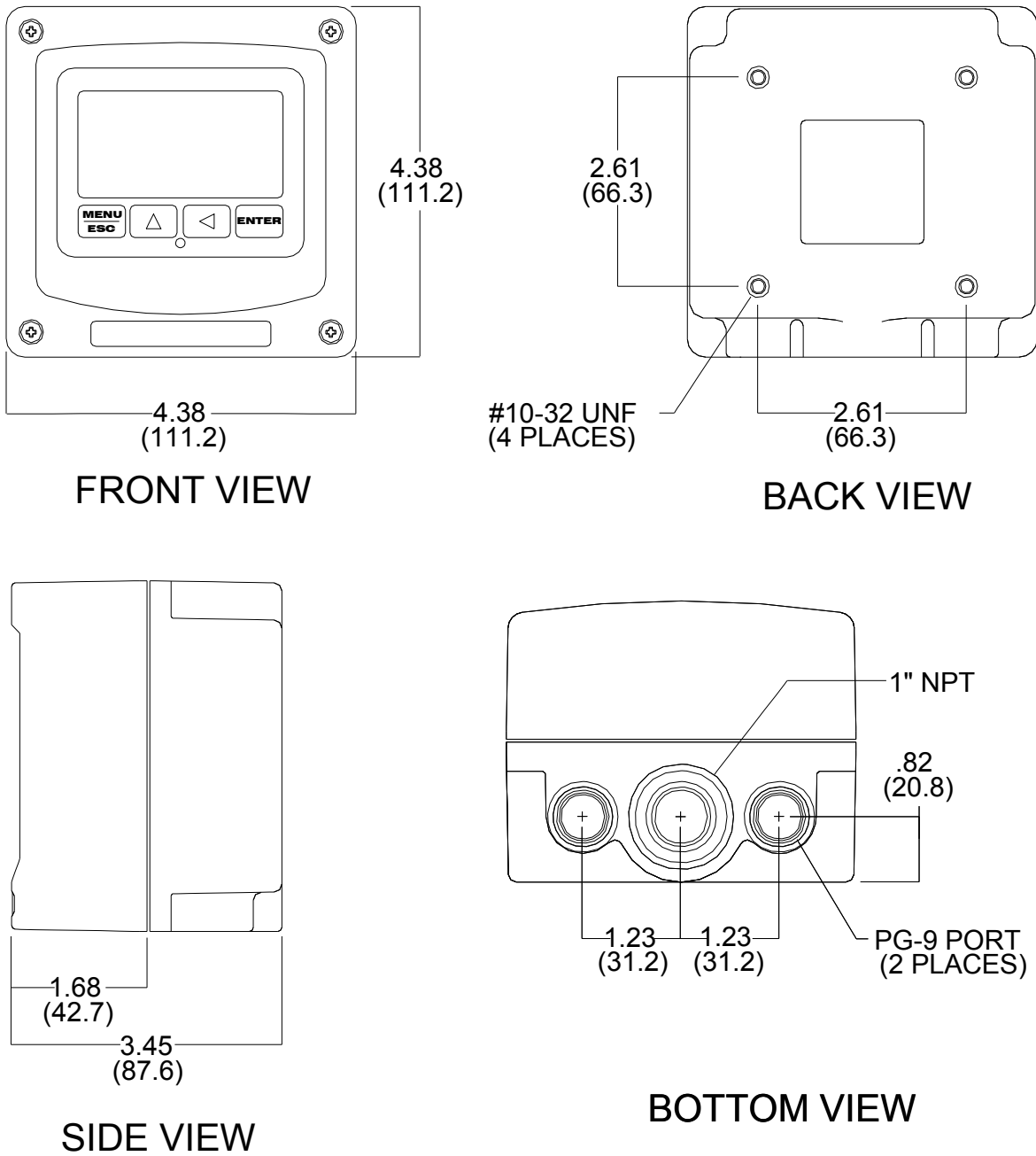
Figure 3 - Enclosure Dimensions, 2-Wire and Battery Units

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2.2   Wall or Pipe Mount

A PVC mounting bracket with attachment screws is supplied with each transmitter (see Figure 4 for dimensions). The multi-purpose bracket is attached to the rear of the enclosure using the four flat head screws. The instrument is then attached to the wall using the four outer mounting holes in the bracket. These holes are slotted to accommodate two sizes of u-bolt that may be used to pipe mount the unit. Slots will accommodate u-bolts designed for 1½ " or 2" pipe. The actual center to center dimensions for the u-bolts are shown in the drawing. Note that these slots are for u-bolts with ¼-20 threads. The 1½" pipe u-bolt (2" I.D. clearance) is available from ATI in type 304 stainless steel under part number 47-0005

6.00
(152.4)

5.46
(138.7)

.250
(6.4)

2.937
(74.6)

3.60
(91.7)

2.375
(60.3)

MOUNTING HOLE
FOR Q SERIES
ENCLOSURE
TYP. 4 PLCS.

MATL: GREY PVC
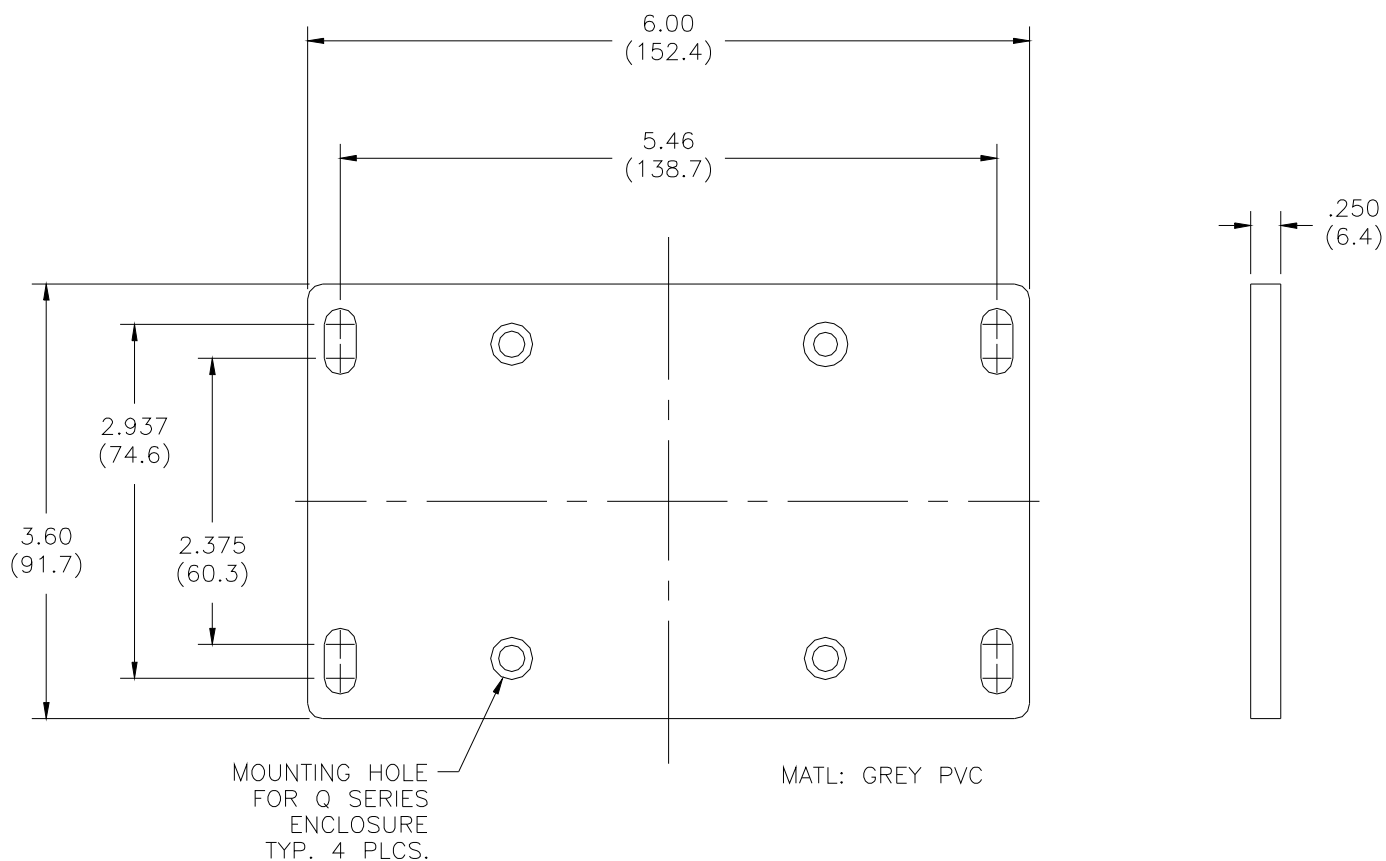
Figure 4 - Wall or Pipe Mount Bracket

6.00
(152.4)

4.875
(123.8)

4.875
(123.8)

2.937
(74.6)
MAX.

2.375
(60.3)
MIN

3.60
(91.44)

MOUNTING SLOT
FOR UP TO 1/4"
DIA. SCREW, TYP
4 PLCS.

MENU
ESC   △   ◁   ENTER

SHOWN WITH 1/2" NPT
CORP GRIPS INSTALLED

5.45
(138.4)
C–C

WALL

3.8
(96)

5.75
(146)
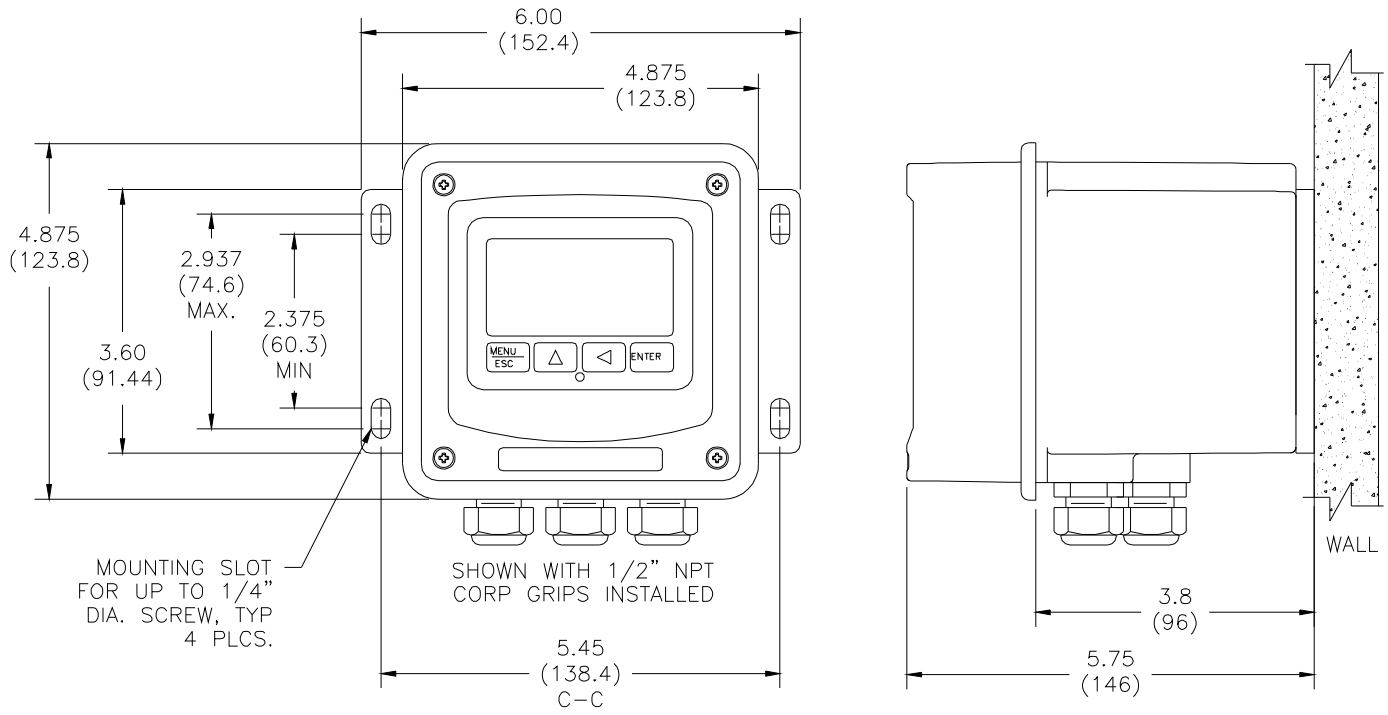
Figure 5 - Wall Mounting Diagram
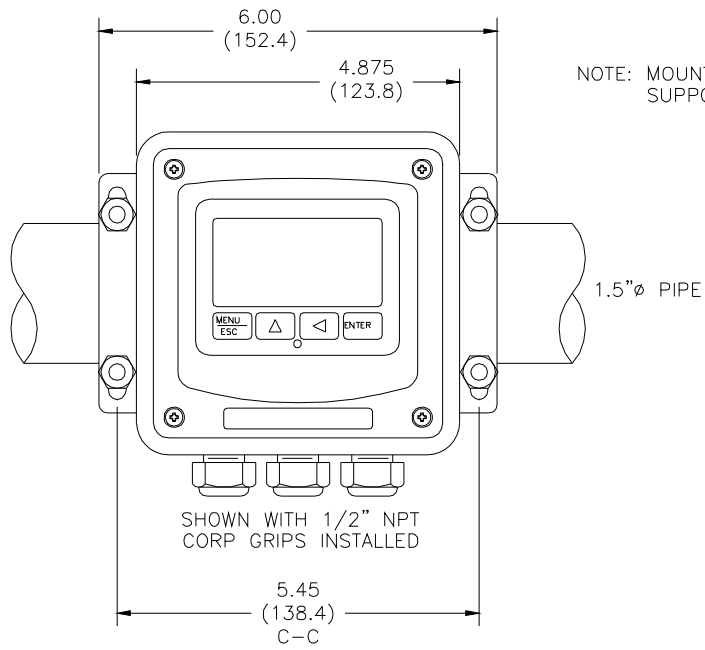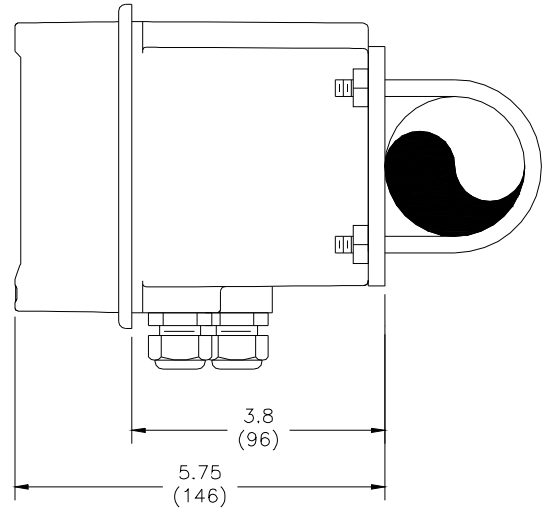
Figure 6 - Pipe Mounting Diagram

2.3   Panel Mounting

Panel mounting of an AC powered monitor uses the panel mounting flange molded into the rear section of the enclosure. Figure 7 provides dimensions for the panel cutout required for mounting. Loop-powered instruments are normally not panel mounted, but may be panel mounted if ordered specifically for this purpose.   Panel mounted 2-wire systems require the use of the "deep back" enclosure normally used for AC powered systems.

The panel mounting bracket kit must be ordered separately (part # 05-0068). This kit contains a metal retainer bracket that attaches to the rear of the enclosure, 4 screws for attachment of this bracket, and a sealing gasket to insure that the monitor provides a water tight seal when mounted to a panel.

The sealing gasket must first be attached to the enclosure. The gasket contains an adhesive on one side to remains in place on the enclosure. Remove the protective paper from the adhesive side of the gasket and slide the gasket over the back of the enclosure so that the adhesive side lines up with the back of the enclosure flange. Once in place, proceed to mount the monitor in the panel.
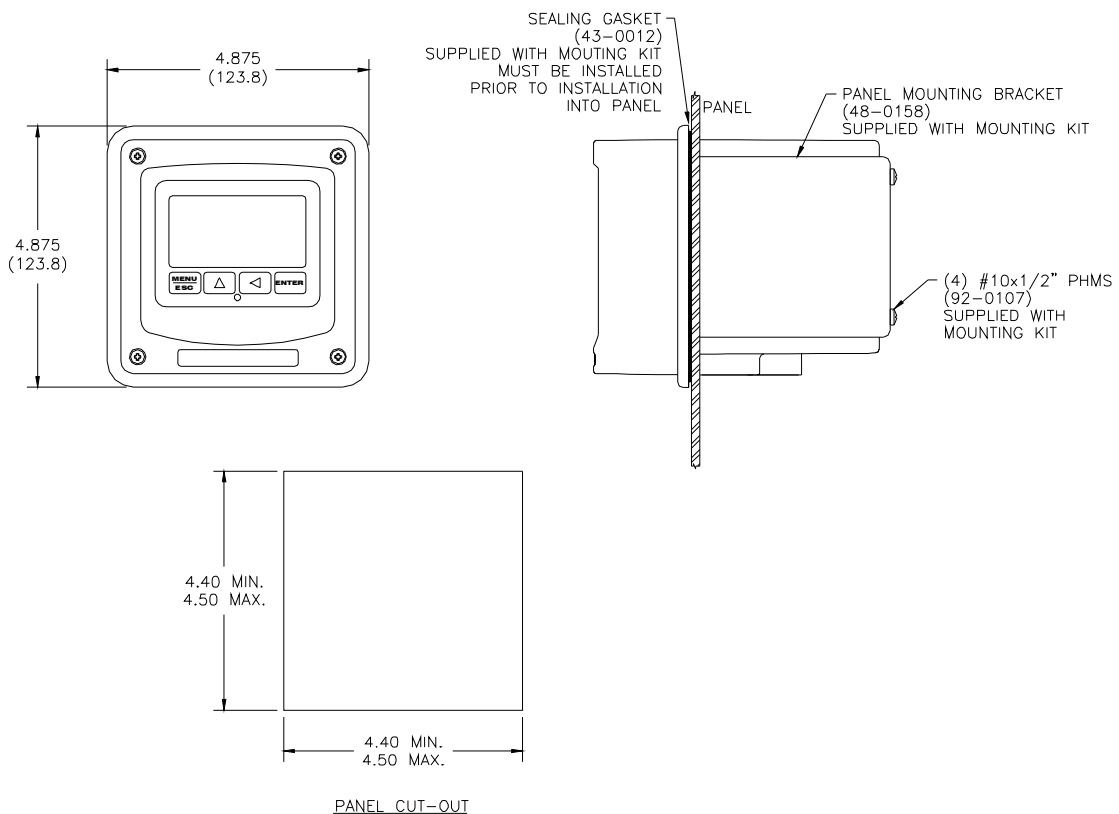
Figure 7 - 115/230 VAC Panel Mount and Cut-Out

Part 3 – Sensor/Flowcell Mounting

3.1 General

Select a location within the maximum sensor cable length for mounting of the sensor flow cell.

3.2 Constant-Head Flowcell

H_2O_2 sensors are best used in a constant-head overflow chamber because variations in sample flow rate and pressure can cause unstable readings. When monitoring low concentrations (below 0.5 PPM), this method should always be used.

Mechanical installation of the flow cell requires that it be mounted to a wall or other convenient flat surface. Alternatively, the mounting holes on the plate will accommodate a 2" U-bolt for mounting the plate to a 2" pipe. Figure 8 shows the dimensions and mounting hole locations for the flow cell. Be sure to allow enough clearance on the left side of the flow cell for insertion and removal of the sensor. About 12 inches clearance is recommended.
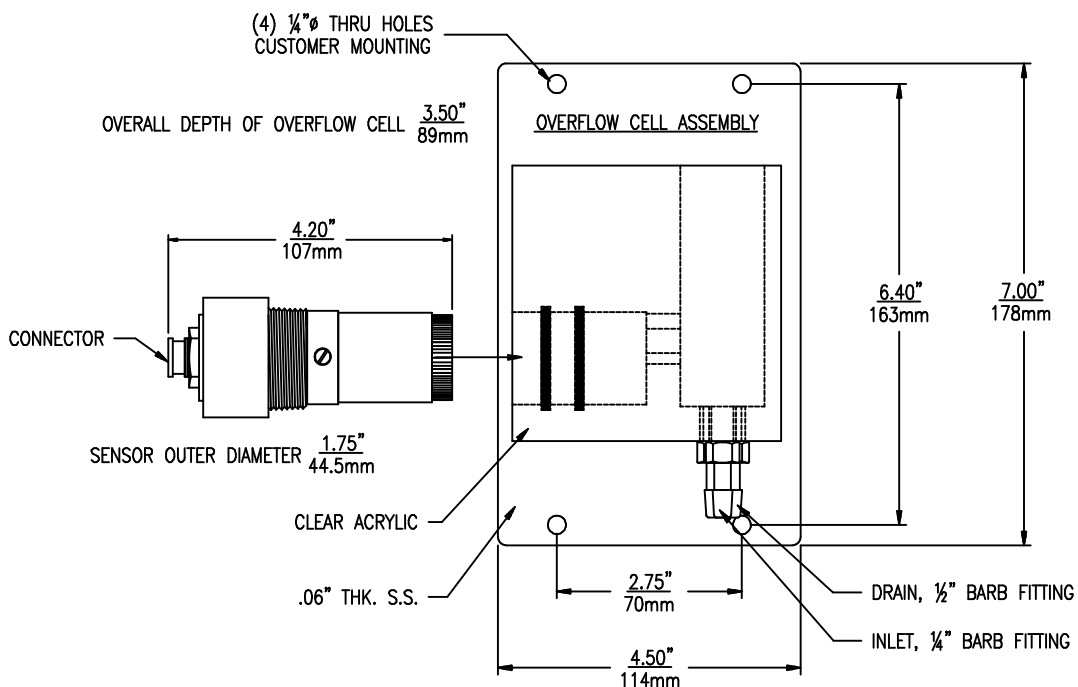
Figure 8 - Constant Head Flowcell Details

Once mounted, inlet and drain connections must be made. The flow cell contains a 1/8" MNPT inlet connection and a 3/8" MNPT drain connection. Hose barbs for the inlet and drain connections are supplied with the flow cell for use with flexible tubing. The inlet hose barb is used with ¼" I.D. tubing and the drain hose barb is used with ½" I.D. tubing.

3.3 Sealed Flowcell

Applications where the sample inlet flow is well controlled can use a simpler sealed flowcell. Using this flowcell requires that flow be controlled externally to about 400 cc/min. Variable flow rate or variable pressure will cause unstable readings in this flowcell. ATI offers a special flow control element that can be used ahead of this flowcell on the incoming sample line. The flow control is part no. (55-0048). It will control the inlet flowrate at 400 cc/min. with inlet pressure variations from 5-150 PSIG. A 50 micron y-strainer ahead of the flow control element is recommended. The sealed flowcell provides a drain vent with check valve to avoid pulling a vacuum on the flow chamber.
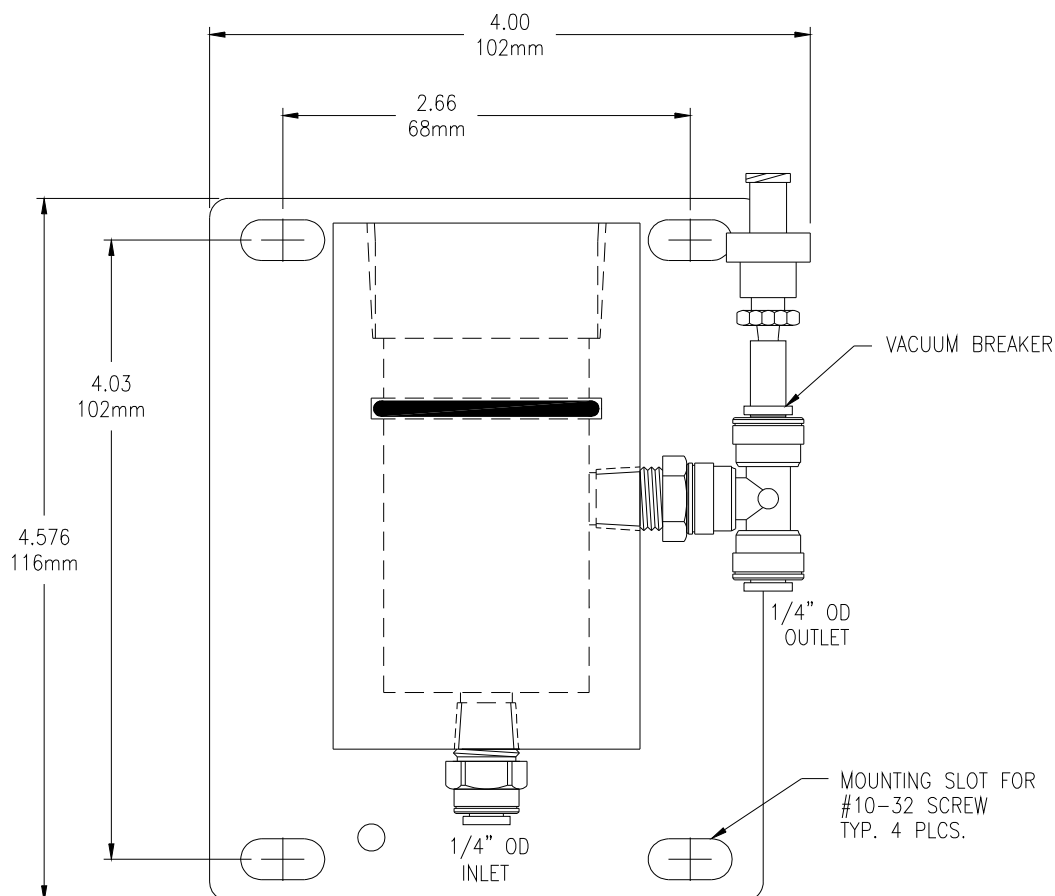
Figure 9 - Sealed Flowcell Details

Part 4 – Electrical Installation

4.1 General

The Q45 is powered in one of two ways, depending on the version purchased. The 2-wire version is a 16-35 VDC powered transmitter. The integral 115/230 VAC version requires line power. DC powered units with relays may be powered from either 12 or 24 VDC regulated power supplies (customer supplied). Please verify the type of unit before connecting any power.

WARNING: Do not connect AC line power to the 2-wire module. Severe damage will result.

Important Notes:

1. Use wiring practices that conform to all national, state and local electrical codes. For proper safety as well as stable measuring performance, it is important that the earth ground connection be made to a solid ground point from terminal 12 (Figure 10). The AC power supply contains a single ¼-Amp slo-blo fuse on the **H** Terminal. The DC powered version contains a 250 mA fuse. The fuse is located adjacent to **TB5** and is easily replaceable.

2. Do NOT run sensor cables or instrument 4-20 mA output wiring in the same conduit that contains AC power wiring. AC power wiring should be run in a dedicated conduit to prevent electrical noise from coupling with the instrumentation signals.

4.2 Two-Wire

In the two-wire configuration, a separate DC power supply must be used to power the instrument. The exact connection of this power supply is dependent on the control system into which the instrument will connect. See Figure 10 for further details. Any twisted pair shielded cable can be used for connection of the instrument to the power supply. Route signal cable away from AC power lines, adjustable frequency drives, motors, or other noisy electrical signal lines. Do not run sensor or signal cables in conduit that contains AC power lines or motor leads.
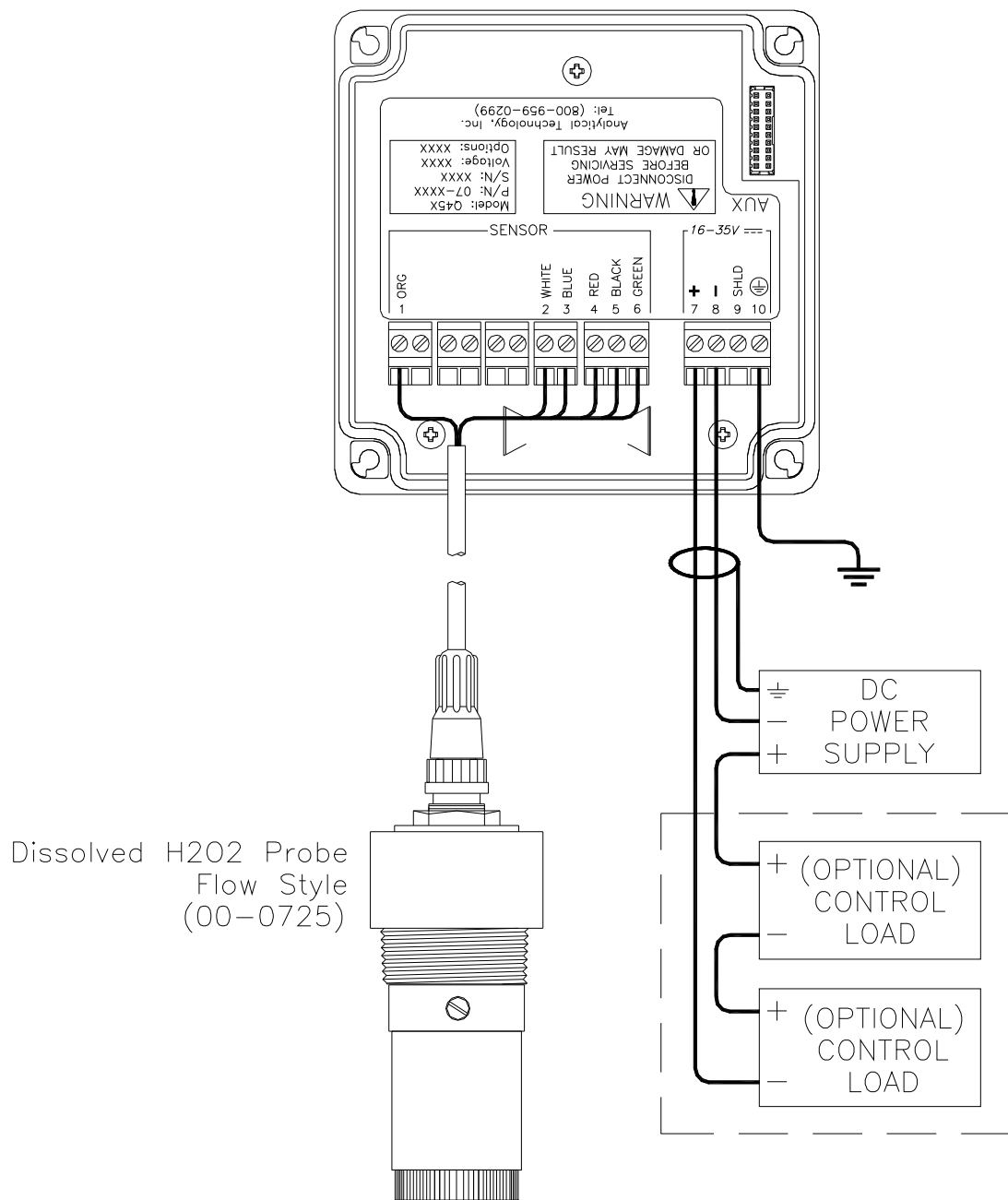
Figure 10 - Loop-Power Connection, Q45 Transmitter

Notes: 1. Voltage between Terminals 7 and 8 MUST be between 16 and 35 VDC.

2. Earth ground into Terminal 9 is HIGHLY recommended. This connection can greatly improve stability in electrically noisy environments.

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4.21   Load Drive

The amount of resistance that the analog output can drive in the 115/230 VAC version is fixed. However, in the two-wire configuration, the load-drive level is dependant on the DC supply voltage provided to the controller.

The two-wire instrument can operate on a power supply voltage of between 16 and 35 VDC. The available load drive capability can be calculated by applying the formula V/I=R, where V=load drive voltage, I=maximum loop current (in Amperes), and R=maximum resistance load (in Ohms).

To find the load drive voltage of the two-wire Q45, subtract 16 VDC from the actual power supply voltage being used (the 16 VDC represents insertion loss). For example, if a 24 VDC power supply is being used, the load drive voltage is 8 VDC.

The maximum loop current of the two-wire Q45 is always 20.00 mA, or .02 A. Therefore,

$$\frac{(\textbf{Power Supply Voltage - 16})}{.02} = \textbf{R}_{\textbf{MAX}}$$

For example, if the power supply voltage is 24 VDC, first subtract 16 VDC, then divide the remainder by .02. 8/.02 = 400; therefore, a 400 Ohm maximum load can be inserted into the loop with a 24 VDC power supply.

Similarly, the following values can be calculated:

Power Supply Voltage (VDC)	Total Load (Ohms)
16.0	0
20.0	200
24.0	400
30.0	700
35.0	950

4.3   115/230 VAC w/Relays

In the 115/230 VAC configuration, a DC power supply is mounted into the inside rear of the enclosure. The power supply must be ordered with the proper operating voltage. Verify that the unit requires either 115 VAC or 230 VAC before installing. Also verify that power is fully disconnected before attempting to wire. Units marked for 115 VAC operation may be safely operated between 90 and 130 VAC. Units marked for 230 VAC operation may be safely operated with input voltages from 180 to 260 VAC.

AC powered Q45 systems are supplied with 3 cable gland fittings and two ½" conduit adapters. One of the cable glands has a larger hole in the rubber gland and should be used for the power cord entry if a flexible power cord will be used for installation. One of the cable glands with the smaller gland opening should normally be used for the sensor cable. Cable glands and conduit hubs will screw into any of the three threaded holes on the bottom of the enclosure.

Connect HOT, NEUTRAL, and GROUND to the matching designations on terminal strip **TB5**.

<div style="background:black;color:white">

WARNING

Disconnect line power voltage BEFORE connecting line power wires to Terminal TB5 of the power supply. The power supply accepts only standard three-wire single phase power. The power supply is configured for 115 VAC or 230 VAC operation at the factory at time of order, and the power supply is labeled as such.   Do NOT connect voltages other than the labeled requirement to the input.

</div>

The analog outputs from the system are present at terminals TB1 and TB2. The loop-load limitation in this configuration is 500 Ohms maximum for each output. Also note that these two outputs are completely isolated from each other to insure that ground loops do not result from the connection of both outputs to the same device such as a PLC or DCS.

In the line-powered unit, a ribbon cable connects the power supply assembly with the microprocessor assembly located in the front section of the enclosure. This cable can be removed during installation to facilitate wiring if desired. It is best to unplug only one end. The ribbon cable has a marking stripe on one edge that is used to indicate proper orientation. The indicator stripe should be on the bottom edge of the cable when installed as shown in Figure 11.
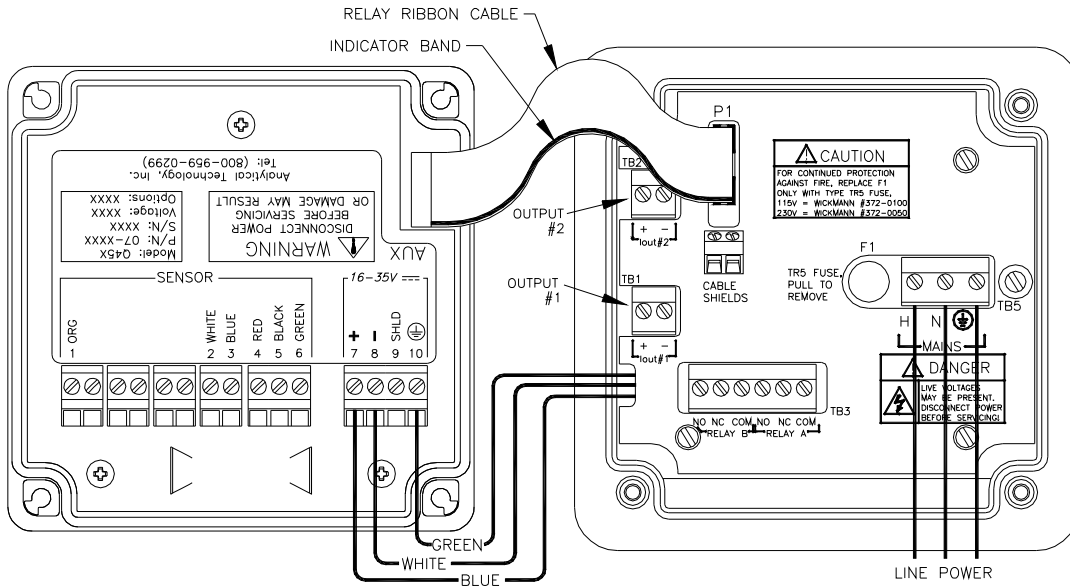
Figure 11 - Line Power Connection

The power strip, **TB5**, allows up to 12 AWG wire. A wire gauge of 16 AWG is recommended to allow for an easy pass-through into the M16 ports when wiring.
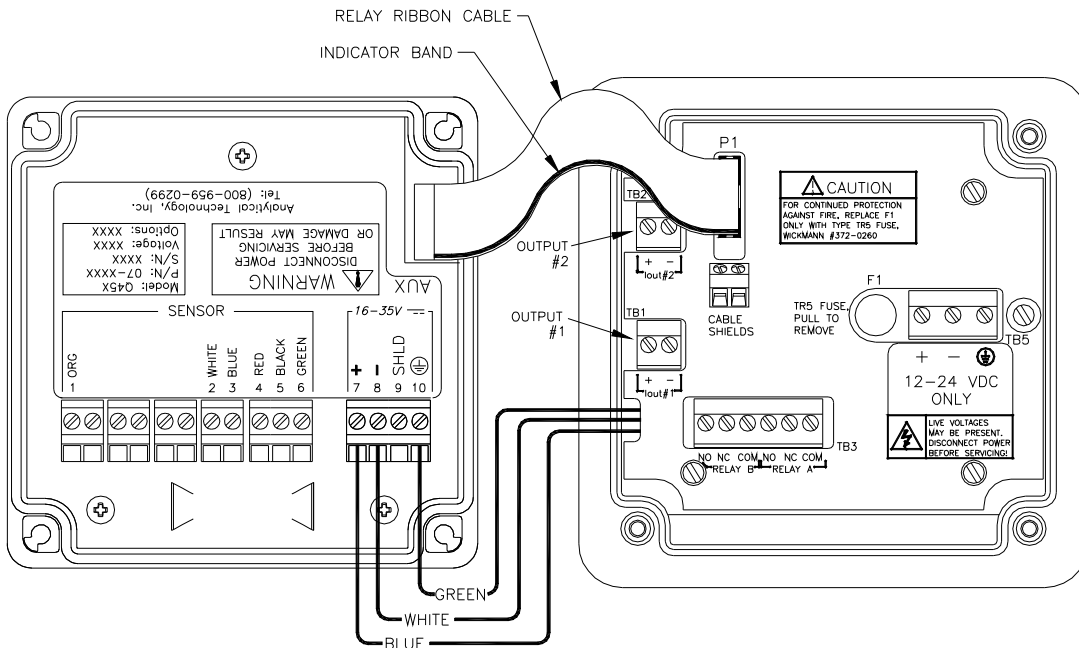
Figure 12 - DC Power Connection

Two sets of SPDT relay contacts are provided on the power supply board. None of the relay contacts are powered. The user must supply the proper power to the contacts. For applications that require the same switched operating voltage as the Q45 (115 or 230 V), power may be jumpered from the power input terminals at **TB5.** Relay wiring is connected at **TB3** as shown below. Note that the relay contact markings are shown in the NORMAL mode. Programming a relay for "Failsafe" operation reverses the NO and NC positions in this diagram.
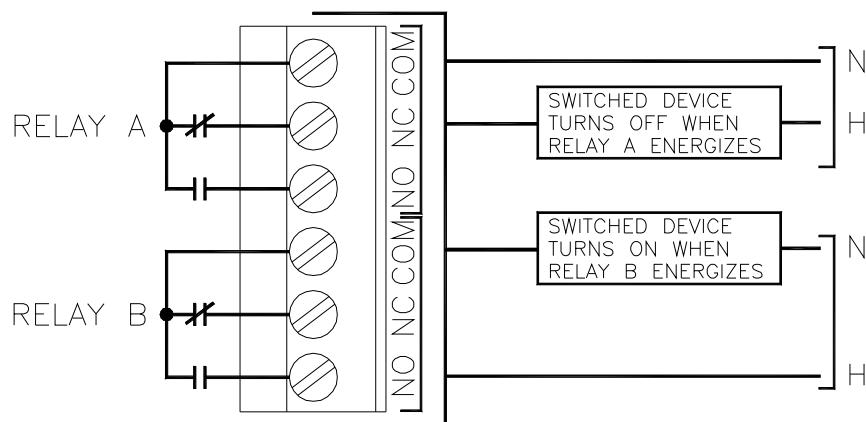
Figure 13 - Relay Contacts

4.4   Sensor Wiring

The sensor cable can be quickly connected to the Q45 terminal strip by matching the wire colors on the cable to the color designations on the label in the monitor. A junction box is also available to provide a break point for long sensor cable runs. Route signal cable away from AC power lines, adjustable frequency drives, motors, or other noisy electrical signal lines. Do not run sensor or signal cables in conduit that contains AC power lines or motor leads.

4.5   Direct Sensor Connection

Sensor connections are made in accordance with Figure 10. The sensor cable can be routed into the enclosure through one of cord-grips supplied with the unit. Routing sensor wiring through conduit is only recommended if a junction box is to be used. Some loose cable is needed near the installation point so that the sensor can be inserted and removed easily from the flowcell.

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Cord-grips used for sealing the cable should be snugly tightened after electrical connections have been made to prevent moisture incursion. When stripping cables, leave adequate length for connections in the transmitter enclosure as shown below. The standard 25 ft. sensor cable normally supplied with the system is already stripped and ready for wiring. This cable can be cut to a shorter length if desired to remove extra cable in a given installation. Do not cut the cable so short as to make installation and removal of the sensor difficult.

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4.00 (101.6) WIRE LENGTH

1.00 (25.4) CABLE LENGTH

CORD GRIP
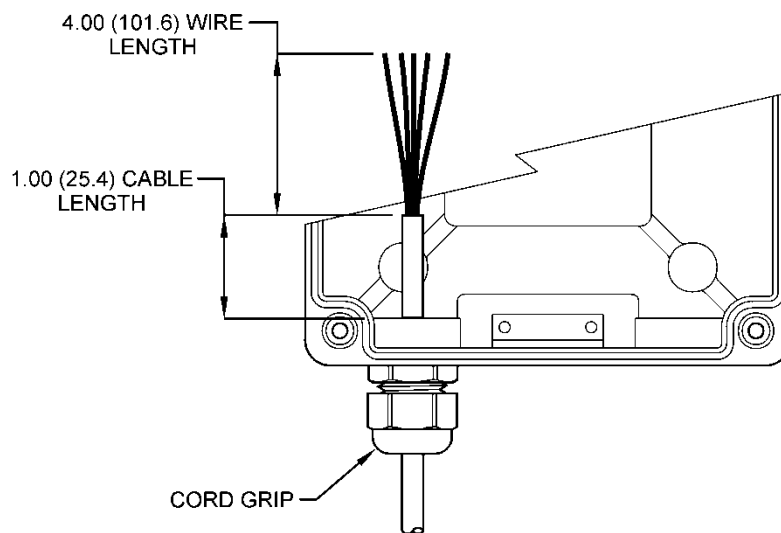
Figure 14 - Sensor Cable Preparation

4.6   Junction Box Connection

For installations where the sensor is to be located more than 25 feet from the monitor (max. 100 feet), a junction box must be used. The junction box is shown in Figure 15, and is supplied with a ½" conduit hub on one end and a sensor cable gland on the other end.
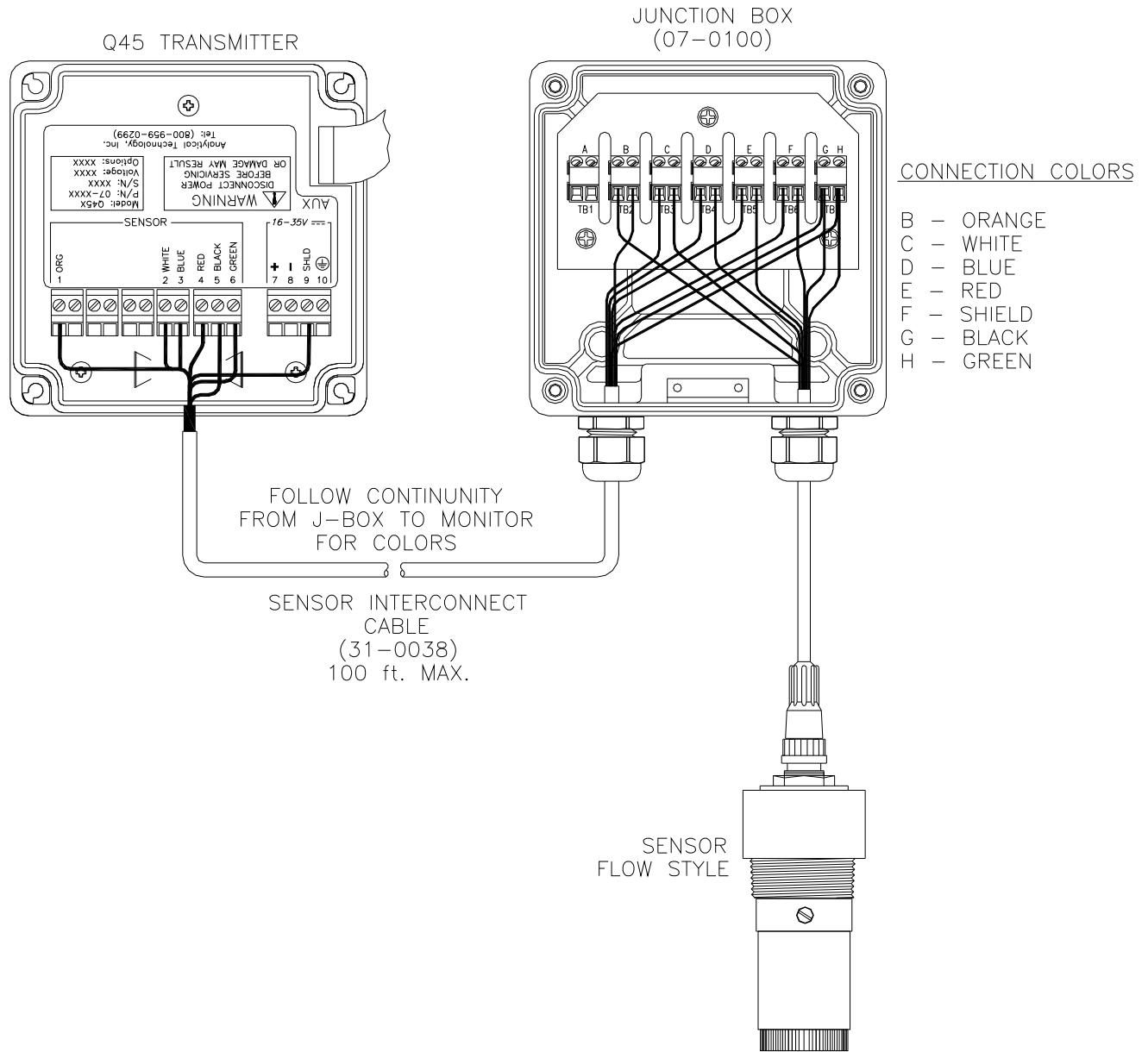
Figure 15 - Junction Box Interconnect Wiring

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Part 5 – Sensor Assembly

5.1   H$_2$O$_2$ Sensor Preparation

The hydrogen peroxide sensor supplied with the Q45/84 is shipped dry. It will not operate until it is prepared by adding electrolyte and a membrane. Preparation of the sensor for operation must be done carefully. The procedure should be done by a qualified technician, and it should only be done when the system is ready for operation. Until then, it is best to leave the sensor in the condition in which it is received.
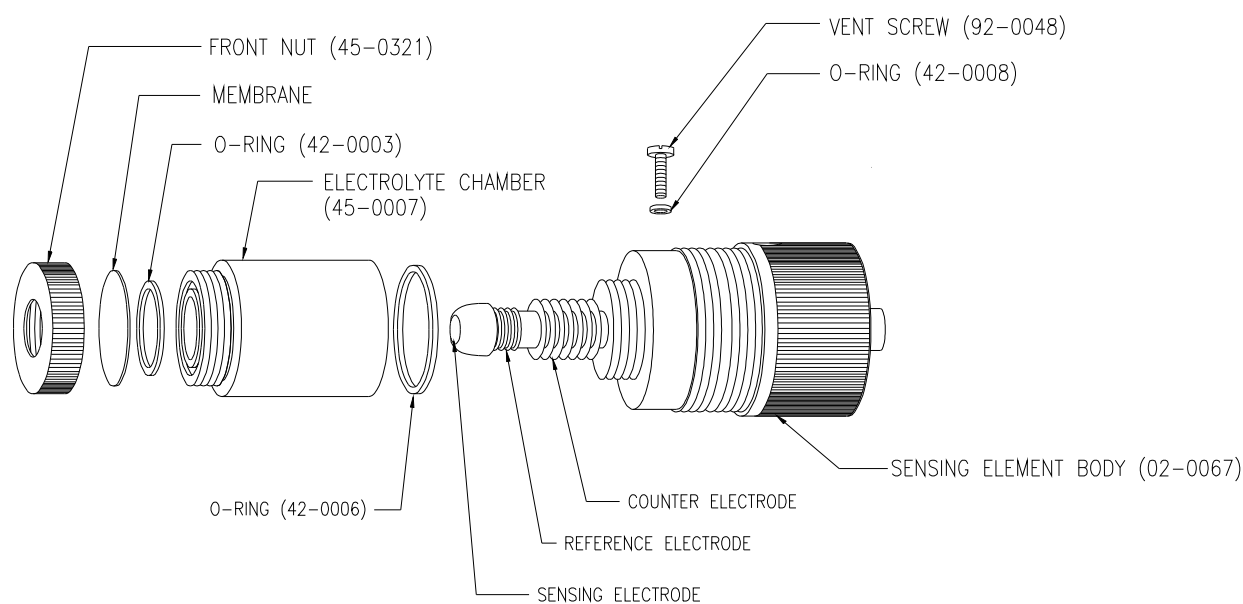
Figure 16 - H2O2 Sensor Assembly

Follow the procedure below to prepare the sensor for operation:

CAUTION: **Use extreme care when filling the H$_2$O$_2$ sensor with electrolyte. The electrolyte is very acidic and can cause eye and skin damage. Getting the electrolyte on clothing will probably result in holes appearing after washing. Wear latex gloves and eye protection when filling the sensor.**

1. Unscrew the electrolyte chamber from the assembled sensor and also remove the vent screw from the side of the sensor body.

2. Remove the front nut from the bottom of the chamber and discard the protective membrane. O-rings are contained in grooves on both the bottom and top of the chamber. Be sure that these o-rings remain in place.

3. From the package of membranes supplied with the sensor, place a new membrane into the front nut. **The membrane is white in color and is separated from other membranes by a light blue paper spacer.**

4. Screw the front nut on to the chamber until you feel the o-ring compress. Hand tight compression is all that is needed. Do not use tools to tighten. The membrane should be flat across the bottom of the chamber without wrinkles.

5. Fill the chamber with electrolyte until the level reaches the bottom of the internal threads.

6. Slowly screw the chamber onto the sensor body. A small amount of electrolyte will run out of the hole from which the vent screw was removed. Place a paper towel around the sensor to absorb the electrolyte overflow. Use **EXTREME** Caution when handling electrolyte. Tighten the chamber until the o-ring at the top of the chamber is compressed. Once again, do not use tools to tighten.

7. Shake excess electrolyte from the fill hole on the side of the sensor and replace the vent screw.

The sensor is now ready for operation. The membrane should be stretched tightly across the tip of the sensor.

CAUTION: **When handling the assembled sensor, do not set the sensor on its tip or damage to the membrane will result. Severe impacts on the tip of the sensor from dropping or other misuse may cause permanent damage to the sensor.**

Part 6 – Configuration

6.1   User Interface

The user interface for the Q45 Series instrument consists of a custom display and a membrane keypad. All functions are accessed from this user interface (no internal jumpers, pots, etc.).

RELAY
INDICATOR

4-DIGIT
MAIN DISPLAY

MENU ICONS

SIGN

UNITS

RELAY/LO-BAT
INDICATOR

12-CHARACTER
SECONDARY
DISPLAY

MEMBRANE
KEYPAD

4-KEY USER
INTERFACE

MENU
ESC

ENTER

MENU/ESCAPE
KEY

ENTER KEY

UP ARROW
KEY

LEFT ARROW
KEY
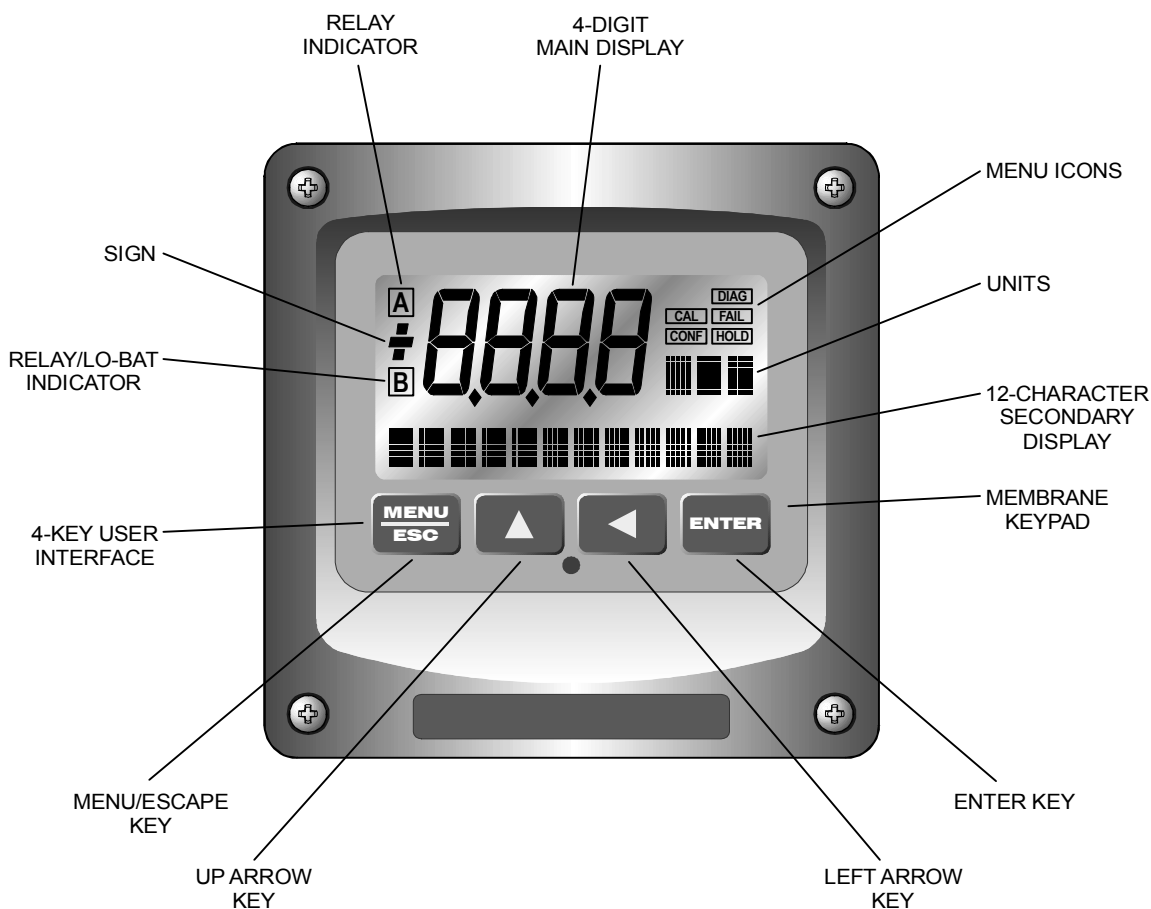
Figure 17 - User Interface

6.11 Keys

All user configuration occurs through the use of four membrane keys. These keys are used as follows:

MENU/ESC   To scroll through the menu section headers or to escape from anywhere in software. The escape sequence allows the user to back out of any changes in a logical manner. Using the escape key aborts all changes to the current screen and backs the user out one level in the software tree. The manual will refer to this key as either MENU or ESC, depending upon its particular function. In the battery-powered version of the Q45, this is also the ON button.

UP (arrow)   To scroll through individual list or display items and to change number values.

LEFT (arrow)   To move the cursor from right to left during changes to a number value.

ENTER   To select a menu section or list item for change and to store any change.

6.12 Display

The large custom display provides clear information for general measurement use and user configuration. There are three main areas of the display: the main parameter display, the secondary message line, and the icon area.

Main Parameter   During normal operation, the main parameter display indicates the present process input with sign and units. This main display may be configured to display any of the main measurements that the system provides. During configuration, this area displays other useful set-up information to the user.

8.24 PPM
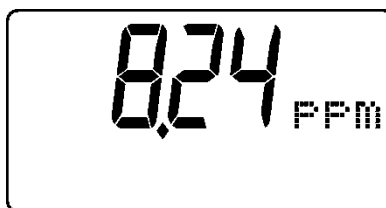
Lower Line   During normal operation, the lower line of the display indicates user-selected secondary measurements that the system is making. This also includes calibration data from the last calibration sequence and the transmitter model number and software version.   During configuration, the lower line displays menu items and set-up prompts to the user.   Finally, the lower line will display error messages when necessary. For a description of all display messages, refer to Section 9.31.

```
+22.8 °C
```
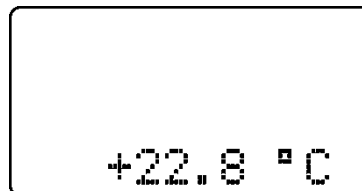
Icon Area   The icon area contains display icons that assist the user in set-up and indicate important states of system functions. The CAL, CONFIG, and DIAG icons are used to tell the user what branch of the software tree the user is in while scrolling through the menu items.   This improves software map navigation dramatically. Upon entry into a menu, the title is displayed (such as CAL), and then the title disappears to make way for the actual menu item. However, the icon stays on.

```
                  [DIAG]
              [CAL] [FAIL]
              [CONF][HOLD]
```

HOLD   The HOLD icon indicates that the current output of the transmitter has been put into output hold. In this case, the output is locked to the last input value measured when the HOLD function was entered.   HOLD values are retained even if the unit power is cycled.

FAIL   The FAIL icon indicates that the system diagnostic function has detected a problem that requires immediate attention. This icon is automatically cleared once the problem has been resolved.

Relay Area A/B   The relay area contains two icons that indicate the state of the system relays (if the relay card is installed). If the battery board is installed instead, the B icon indicates that the battery voltage is at a low level. The battery power option and the relay option cannot be installed together.

6.2   Software

The software of the Q45H is organized in an easy to follow menu-based system. All user settings are organized under five menu sections: Measure, Calibration [**CAL**], Configuration [**CONFIG**], Control **[CONTROL]** and Diagnostics [**DIAG**].

Note: **The default Measure Menu is display-only and has no menu icon.**

6.21   Software Navigation

Within the CAL, CONFIG, CONTROL, and DIAG menu sections is a list of selectable items. Once a menu section (such as CONFIG) has been selected with the MENU key, the user can access the item list in this section by pressing either the ENTER key or the UP arrow key. The list items can then be scrolled through using the UP arrow key. Once the last item is reached, the list wraps around and the first list item is shown again. The items in the menu sections are organized such that more frequently used functions are first, while more permanent function settings are later in the list. See Figure 18 for a visual description of the software.

Each list item allows a change to a stored system variable. List items are designed in one of two forms: simple single variable, or multiple variable sequence. In the single variable format, the user can quickly modify one parameter - for example, changing temperature display units from °F to °C. In the multiple variable sequence, variables are changed as the result of some process. For example, the calibration of H_2O_2 generally requires more than one piece of information to be entered. The majority of the menu items in the software consist of the single variable format type.

Any data that may be changed will be flashing. This flashing indicates user entry mode and is initiated by pressing the ENTER key. The UP arrow key will increase a flashing digit from 0 to 9. The LEFT arrow key moves the flashing digit from right to left. Once the change has been completed, pressing ENTER again stores the variable and stops the flashing. Pressing ESC aborts the change and also exits user entry mode.

The starting (default) screen is always the Measure Menu. The UP arrow key is used to select the desired display. From anywhere in this section the user can press the MENU key to select one of the four Menu Sections.

The UP arrow icon next to all list items on the display is a reminder to scroll through the list using the UP arrow key.

To select a list item for modification, first select the proper menu with the MENU key. Scroll to the list item with the UP arrow key and then press the ENTER key. This tells the system that the user wishes to perform a change on that item. For single item type screens, once the user presses the ENTER key, part or all of the variable will begin to flash, indicating that the user may modify that variable using the arrow keys. However, if the instrument is locked, the transmitter will display the message **Locked!** and will not enter user entry mode. The instrument must be unlocked by entering the proper code value to allow authorized changes to user entered values. Once the variable has been reset, pressing the ENTER key again causes the change to be stored and the flashing to stop. The message **Accepted!** will be displayed if the change is within pre-defined variable limits. If the user decides not to modify the value after it has already been partially changed, pressing the ESC key aborts the modification and returns the entry to its original stored value.

In a menu item which is a multiple variable sequence type, once the ENTER key is pressed there may be several prompts and sequences that are run to complete the modification. The ESC key can always be used to abort the sequence without changing any stored variables.
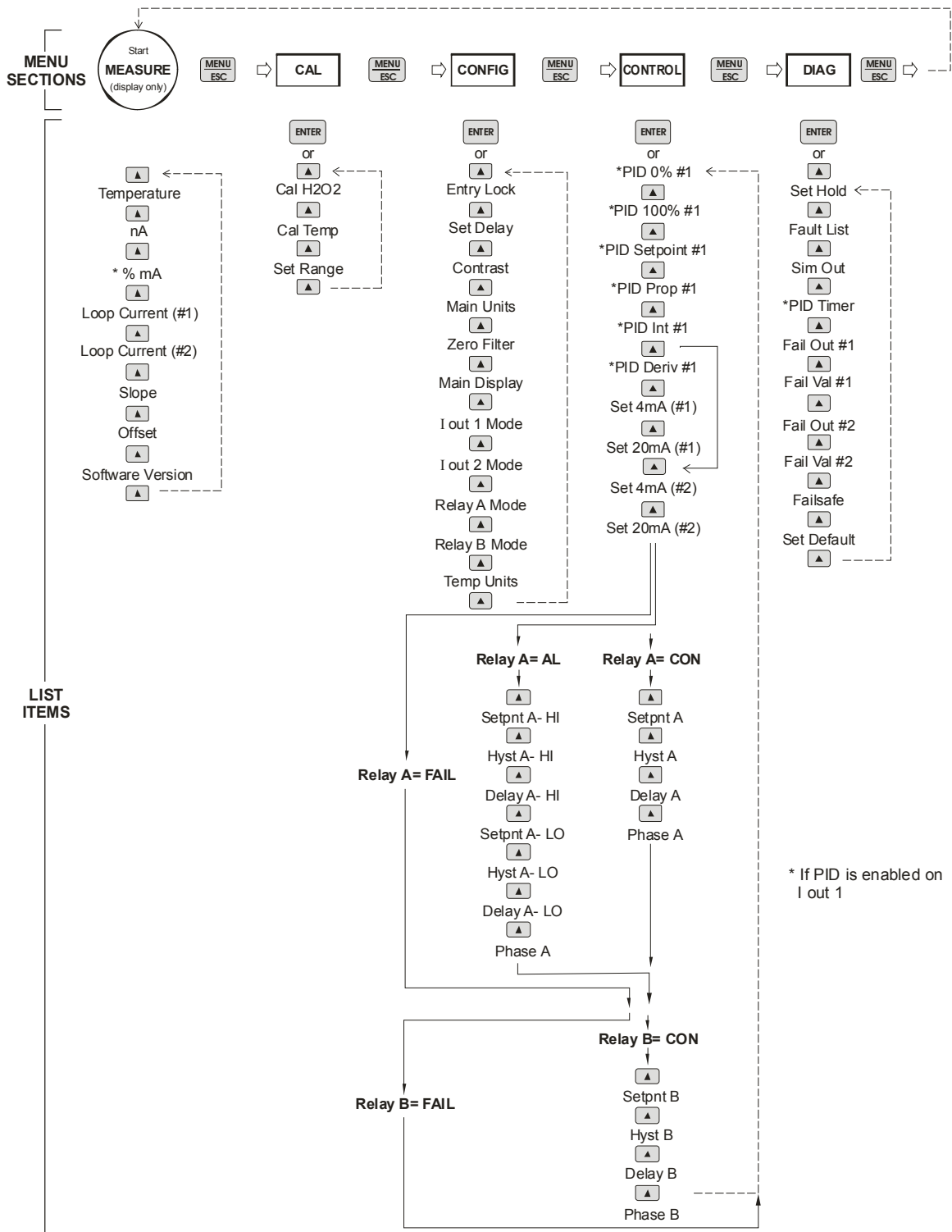
Figure 18 - Software Map

6.22 Measure Menu [MEASURE]

The default menu for the system is the display-only menu MEASURE. This menu is a display-only measurement menu, and has no changeable list items. When left alone, the instrument will automatically return to this menu after approximately 30 minutes. While in the default menu, the UP arrow allows the user to scroll through the secondary variables on the lower line of the display. A brief description of the fields in the basic transmitter version is as follows:

TRANSMITTER MEAS SCREENS:

25.7C   Temperature display. Can be displayed in C or F, depending on user selection. A small "m" on the left side of the screen indicates the transmitter has automatically jumped to a manual 25C setting due to a failure with the temperature signal input.

32.0 nA   Raw sensor current. Useful for diagnosing problems.

100% 20.00 mA   PID Status screen (if enabled.) Shows the present controller output level on left, and actual transmitter current on the right. The controller can be placed in manual while viewing this screen by pressing and holding the ENTER key for 5 seconds until a small flashing "m" appears on the screen. At that point the controller output can be adjusted up or down using the UP and LEFT arrow keys. To return to automatic operation, press and hold the ENTER key for 5 seconds and the "M" will disappear.

20.00 mA   Transmitter output current.

Slope = 100%   Sensor output response vs. ideal calibration. This value updates after each calibration. As the sensor ages, the slope reading will decay indicating sensor aging. Useful for resolving sensor problems.

Offset = 0.0 nA   Sensor output current at a zero ppm input. This value updates after a zero-calibration has been performed. Useful for resolving sensor problems.

Q45S5 v4.02   Transmitter software version number.

> **Note: A display test (all segments ON) can be actuated by pressing and holding the ENTER key while viewing the model/version number on the lower line of the display.**

For the relay-based analyzer version, or the portable battery powered version of the transmitter, the screens are basically the same, with additions to show two analog output instead of one (#1 and #2.)

The MEASURE screens are intended to be used as a very quick means of looking up critical values during operation or troubleshooting.

6.23 Calibration Menu [CAL]

The calibration menu contains items for frequent calibration of user parameters. There are four items in this list: Cal H_2O_2, Cal Temp, Set Range, and Cal Zero.

Cal H_2O_2   The H_2O_2 calibration function allows the user to adjust the transmitter span reading to match a reference solution, or to set the sensor zero point. See Part 7 - Calibration for more details.

Cal Temp   The temperature calibration function allows the user to adjust the offset of the temperature response by a small factor of ±5 ˚C. The temperature input is factory calibrated to very high accuracy. However, long cable lengths and junction boxes may degrade the accuracy of the temperature measurement in some extreme situations. Therefore, this feature is provided as an adjustment. See Part 7 - Calibration for more details.

Set Range   This function allows the user to set the display range of the transmitter to a specific application. Once set, all output functions use this display range to establish configuration settings. Press ENTER to initiate user entry mode, and the value will flash. Use the arrow keys to modify value; available ranges include 2.000 ppm, 20.00 ppm, and 200.0 ppm. Press ENTER to store the new value. The display range does not affect the internal auto ranging scaler that, therefore, sensitivity is to specification in any user selected range.

6.24   Configuration Menu [CONFIG]

The Configuration Menu contains all of the general user settings:

Entry Lock   This function allows the user to lock out unauthorized tampering with instrument settings. All settings may be viewed while the instrument is locked, but they cannot be modified. The Entry Lock feature is a toggle-type setting; that is, entering the correct code will lock the transmitter and entering the correct code again will unlock it. The code is preset at a fixed value. Press ENTER to initiate user entry mode and the first digit will flash. Use arrow keys to modify value. **See Page 81 for the Q45H lock/unlock code.** Press ENTER to toggle lock setting once code is correct. Incorrect codes do not change state of lock condition.

Set Delay   The delay function sets the amount of damping on the instrument. This function allows the user to apply a first order time delay function to the H_2O_2 measurements being made. Both the display and the output value are affected by the degree of damping. Functions such as calibration are not affected by this parameter. The calibration routines contain their own filtering and stability monitoring functions to minimize the calibration timing. Press ENTER to initiate user entry mode, and the value will flash. Use the arrow keys to modify value; range is 0.1 to 9.9 minutes. Press ENTER to store the new value.

Contrast   This function sets the contrast level for the display. The custom display is designed with a wide temperature range, Super-Twist Nematic (STN) fluid.

The STN display provides the highest possible contrast and widest viewing angle under all conditions. Contrast control of this type of display is generally not necessary, so contrast control is provided as a means for possible adjustment due to aging at extreme ranges. In addition, the display has an automatic temperature compensation network. Press ENTER to initiate user entry mode, and the value will flash. Use arrow keys to modify the value; range is 0 to 8 (0 being lightest). Press ENTER to update and store the new value.

Top Display   This function allows the user to change the measurement in the primary display area. The user may select between H_2O_2, sensor temperature, or output current. Using this function, the user may choose to put temperature in the main display area and H_2O_2 on the secondary, lower line of the display. Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired display value. Press ENTER to store the new value.

Iout#1 Mode   This function sets analog output #1 to either track H_2O_2 (default) or enables the PID controller to operate on the H_2O_2 input. Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired value; selections include 1-ppm for H_2O_2 tracking or 2-PID for H_2O_2 PID control. Press ENTER to store the new value.

<u>**AC OPERATED UNITS ONLY**</u>

*Iout#2 Mode   This function sets analog output #2 for either temperature (default), H_2O_2, or pH. Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired value; selections include 1-C/F for temperature, 2-ppm for H_2O_2, or 3-pH for pH. Press ENTER to store the new value.

<u>**AC OPERATED UNITS ONLY**</u>

*Rly A Mode   Relay A can be used in three different ways: as a setpoint control, as a fail alarm, or as a HI-LO alarm band. The three settings for Rly A Mode are **CON**, **FAIL** and **AL**.

                 The **CON** setting enables normal control operation for Relay A, with settings for setpoint, hysteresis, delay and phasing appearing in the CONFIG menu automatically. See Figure 19 for further details.

                 The **FAIL** setting enables the fail alarm mode for Relay A. Relay A will then trip on any condition that causes the FAIL icon to be displayed on the LCD. Using this mode allows the User to send alarm indications to other remote devices.

                 The **AL** setting allows two setpoints to be selected for the same relay, producing a HI-LO alarm band. In this mode, Relay A will trip inside or outside of the band, depending upon the Phase selected. See Figure 20 for further details.

<u>**AC OPERATED UNITS ONLY**</u>

*Relay B Mode   Relay B can be used in a number of ways: as a setpoint control, or as an alarm. The two settings for Relay B Mode are **CON** and **FAIL**.

The **CON** setting enables normal setpoint operation for Relay B. Relay B then operates identically to Relay A, with settings for setpoint, hysteresis, delay and phasing appearing in the CONFIG menu automatically. See Figure 19 for details.

The **FAIL** setting enables the fail alarm mode for Relay B. Relay B will then trip on any condition that causes the FAIL icon to be displayed on the LCD. Using this mode allows the User to send alarm indications to other remote devices. Figure 20 for details.

Temp Units   This function sets the display units for temperature measurement. Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired display value. The choices are **°F** and **°C**. Press ENTER to store the new value.

6.25   Control Menu [CONTROL]

The Control Menu contains all of the output control user settings:

Set 4 mA
Set 20 mA
[Iout1= H_2O_2]   These functions set the main 4 and 20 mA current loop output points for the transmitter. The units displayed depend on the selection made in the CONFIG menu for Iout #1 Mode. Also, when the Relay Option Board is installed, the units will also display **#1 or #2** – since there are actually two analog outputs present in this version.

The value stored for the 4 mA point may be higher or lower than the value stored for the 20 mA point. The entry values are limited to values within the range specified in "Set Range", and the 4 mA and the 20 mA point must be separated by at least 1% of this range Use the LEFT arrow key to select the first digit to be modified. Then use the UP and LEFT arrow keys to select the desired numerical value. Press ENTER to store the new value.

Set PID 0%
Set PID 100%
[Iout1=PID]   If the PID is enabled, this function sets the minimum and maximum controller end points. Unlike the standard 4-20 mA output, the controller does not "scale" output values across the endpoints. Rather, the endpoints determine where the controller would normally force minimum or maximum output in an attempt to recover the setpoint (even though the controller can achieve 0% or 100% anywhere within the range.)

If the 0% point is lower than the 100% point, then the controller action will be "reverse" acting. That is, the output of the controller will increase if the measured value is less than the setpoint, and the output will decrease if the measured value is larger than the setpoint. Flipping the stored values in these points will reverse the action of the controller to "direct" mode.

The entry value is limited to a value within the range specified in "Set Range", and the 0% and the 100% point must be separated by at least 1% of this range Use the LEFT arrow key to select the first digit to be modified. Then use the UP and LEFT arrow keys to select the desired numerical value. Press ENTER to store the new value.

PID Setpnt
[Iout1=PID]   The measured value which the controller is attempting to maintain by adjusting output value. It is the nature of the PID controller that it never actually gets to the exact value and stops. The controller is continually making smaller and smaller adjustments as the measured value gets near the setpoint.

PID Prop
[Iout1=PID]   Proportional gain factor. The proportional gain value is a multiplier on the controller error (difference between measured value and setpoint value.) Increasing this value will make the controller more responsive.

PID Int
[Iout1=PID]   Integral is the number of "repeats-per-minute" of the action of the controller. It is the number of times per minute that the controller acts on the input error. At a setting of 2.0 rpm, there are two repeats every minute. If the integral is set to zero, a fixed offset value is added to the controller (manual reset.) Increasing this value will make the controller more responsive.

PID Deriv
[Iout1=PID]   Derivative is a second order implementation of Integral, used to suppress "second-order" effects from process variables. These variables may include items like pumps or mixers that may have minor impacts on the measured value. The derivative factor is rarely used in water treatment process, and therefore, it is best in most cases to leave it at the default value. Increasing this value will make the controller more responsive.

<u>**AC POWERED UNITS ONLY**</u>

*Set 4 mA #2
*Set 20 mA #2
[temp/ H_2O_2]   These functions set the second 4 mA and 20 mA current loop output points for the transmitter. The output may be set to track temperature (default), or H_2O_2. The values stored for the 4 mA point may be higher or lower than the value stored for the 20 mA point.

The entry value is limited to a value between 0 and 55 °C if it is set for temperature, within the range specified in "Set Range" if the output is set to track H_2O_2. The 4 mA and the 20 mA point must be at least 20 units away from each other. Press ENTER to initiate user entry mode, and the value will flash. Use arrow keys to modify value. Press ENTER to store the new value.

*NOTE: I*f the temperature units are changed between °C and °F (see Temp Units in this section), the default settings for this output will be stored (present data is not converted.)

<u>**ALARM CONFIGURATIONS APPLY TO AC POWERED UNITS ONLY**</u>

*A Setpoint   This function establishes the H_2O_2 trip point for relay A. The entry value is limited to a value within the range specified in "Set Range". Use the LEFT arrow key to select the first digit to be modified. Then use the UP and LEFT arrow keys to select the desired numerical value. Press ENTER to store the new value.

*A Hysteresis   This function establishes the hysteresis, or "deadband", for Relay A. Hysteresis is most often used to control relay chattering; however, it may also be used in control schemes to separate the ON/OFF trip points of the relay. Press ENTER to initiate user entry mode, and the value will flash. Use the arrow keys to modify value. Press ENTER to store the new value.

*A Delay   This function places an additional amount of time delay on the trip point for relay A. This delay is in addition to the main delay setting for the controller. The entry value is limited to a value between 0 and 999 seconds. Press ENTER to initiate user entry mode, and the value will flash. Use arrow keys to modify value; range is 0 to 999 seconds. Press ENTER to store the new value.

*A Phasing   This function establishes the direction of the relay trip. When phase is HI, the relay operates in a direct mode. Therefore, the relay energizes and the LCD indicator illuminates when the H_2O_2 value **exceeds** the setpoint. When the phase is LO, the relay energizes and the LCD indicator illuminates when the H_2O_2 level drops **below** the setpoint. The failsafe setting does have an impact on this logic. The description here assumes the failsafe setting is OFF. Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired value; selections include **HI** for direct operation or **LO** for reverse operation. Press ENTER to store the new value.

See Figure 19 below for a visual description of a typical control relay application.

When value rises to ≥ 1.000 ppm, relay closes.   When value rises to ≥ 1.050 ppm, relay opens.

When value falls to ≤ 0.950 ppm, relay opens.   When value falls to ≤ 1.000 ppm, relay closes.

Settings:

Setpoint: 1.000 ppm
Hyst: 0.050
Delay: 000
Failsafe: OFF
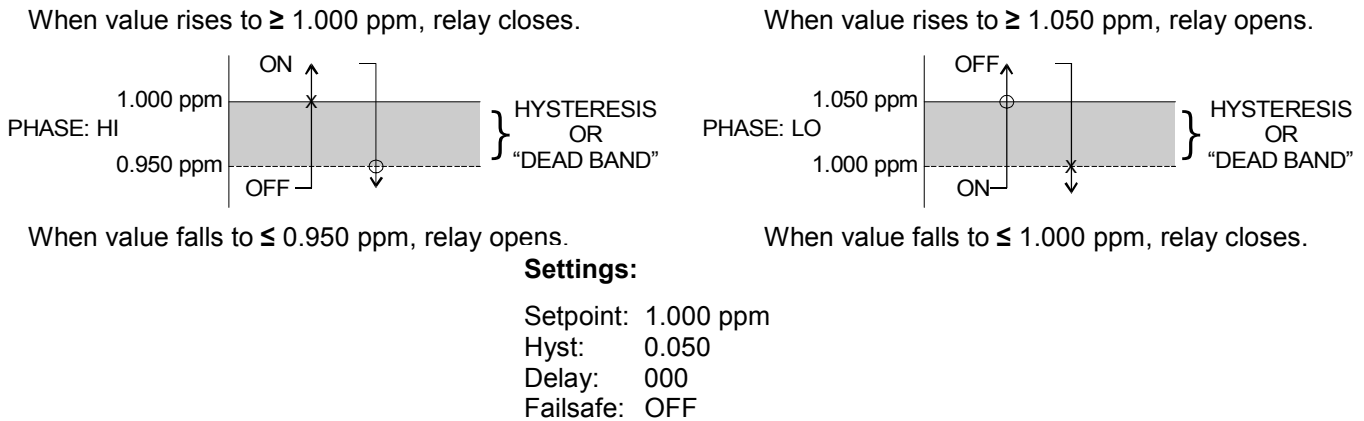
Figure 19 - Control Relay Example, Hysteresis and Opposite Phase Options

<div style="border: 1px solid black">

*Setpnt A-HI
*Hyst A-HI
*Delay A-HI
*Setpnt A-LO
*Hyst A-LO
*Delay A-LO

</div>

If Relay A Mode is set to Alarm Mode, **AL**, then the following settings will appear in the Config Menu list automatically. In this mode, two setpoints can be selected on the same relay, to create an alarm band. Phase HI selection causes the relay to energize outside of the band, and Phase LO causes the relay to energize inside of the band. This feature enables one relay to be used as a control relay while the other is used as a HI-LO Alarm relay at the same time. Setpoint A-LO must be set lower than Setpoint A-HI. When AL mode is first selected, Setpoint A-LO is defaulted to 0.

Figure 20 is a visual description of a typical alarm relay application.

When value rises to ≥ 1.000 ppm, relay closes, until value falls back to ≤ 0.950 ppm.

When value falls to ≤ 1.000 ppm, relay closes, until rises back to ≥ 1.050 ppm.

When value falls to ≤ 0.500 ppm, relay closes, until rises back to ≥ 0.550 ppm.

When value rises to ≥ 0.500 ppm, relay closes, until value falls back to ≤ 0.450 ppm.
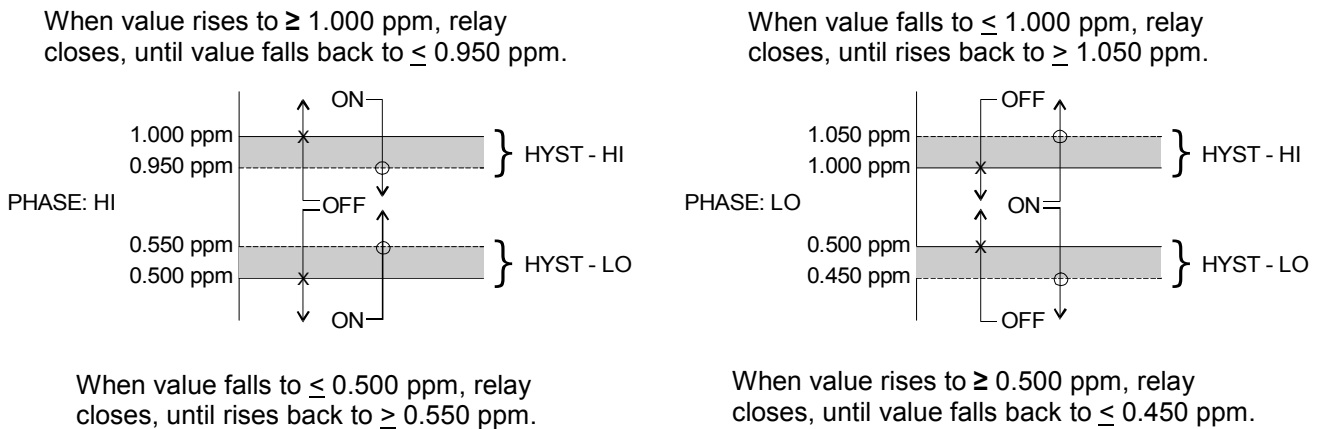
Settings:

Setpoint A-HI: 1.000 ppm   Setpoint A-LO: .500 ppm
Hyst   A-HI: 0.050   Hyst   A-LO: .0.050
Delay   A-HI: 000   Delay   A-LO: 000

Figure 20 - Alarm Relay Example

<div style="border: 1px solid black">

*B Setpoint
*B Hysteresis
*B Delay
*B Phasing

</div>

If Relay B Mode is set to **CON** (see **Relay B Mode**, page 52), then Relay B will function identically to Relay A CON mode described earlier. Relay B settings appear in the CONFIG menu list automatically.

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6.26 Diagnostics Menu [DIAG]

The diagnostics menu contains all of the user settings that are specific to the system diagnostic functions, as well as functions that aid in troubleshooting application problems.

Set Hold   The Set Hold function locks the current loop output values on the present process value. This function can be used prior to calibration, or when removing the sensor from the process, to hold the output in a known state. Once HOLD is released, the outputs return to their normal state of following the process input. The transfer out of HOLD is bumpless on the both analog outputs - that is, the transfer occurs in a smooth manner rather than as an abrupt change. An icon on the display indicates the HOLD state, and the HOLD state is retained even if power is cycled. Press ENTER to initiate user entry mode, and entire value will flash. Use the UP arrow key to modify the desired value, selections are **ON** for engaging the HOLD function, and **OFF** to disengage the function. Press ENTER to store the new value.

Note: When the Relay Option Board is installed, the Set Hold function holds BOTH current levels, as well as ALL relay settings.

The Set Hold function can also hold at an output value specified by the user. To customize the hold value, first turn the HOLD function on. Press the ESC key to go to the DIAG Menu and scroll to Sim Output using the UP arrow key. Press ENTER. Follow the instructions under Sim Output (see following page).

Fault List   The Fault List screen is a read-only screen that allows the user to display the cause of the highest priority failure. The screen indicates the number of faults present in the system and a message detailing the highest priority fault present. Note that some faults can result in multiple displayed failures due to the high number of internal tests occurring. As faults are corrected, they are immediately cleared.

Faults are not stored; therefore, they are immediately removed if power is cycled. If the problem causing the faults still exists, however, faults will be displayed again after power is re-applied and a period of time elapses during which the diagnostic system re-detects them.   The exception to this rule is the calibration failure. When a calibration fails, no corrupt data is stored. Therefore, the system continues to function normally on the data that was present before the calibration was attempted.

After 30 minutes or if power to the transmitter is cycled, the failure for calibration will be cleared until calibration is attempted again. If the problem still exists, the calibration failure will re-occur. Press ENTER to initiate view of the highest priority failure. The display will automatically return to normal after a few seconds.

PID Timer   This function sets a timer to monitor the amount of time the PID controller remains at 0% or 100%. This function only appears if the PID controller is enabled. If the timer is set to 0000, the feature is effectively disabled. If the timer value is set to any number other zero, a FAIL condition will occur if the PID controller remains at 0% or 100% for the timer value. If one of the relays are set to FAIL mode, this failure condition can be signaled by a changing relay contact.

Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify desired value; range of value is 0-9999 seconds. Press ENTER to store the new value.

Sim Out   The Sim Out function allows the user to simulate the H_2O_2 level of the instrument in the user selected display range. The user enters a ppm value directly onto the screen, and the output responds as if it were actually receiving the signal from the sensor. This allows the user to check the function of attached monitoring equipment during set-up or troubleshooting. Escaping this screen returns the unit to normal operation. Press ENTER to initiate the user entry mode, and the right-most digit of the value will flash. Use arrow keys to modify desired value.

The starting display value will be the last read value of the input. The output will be under control of the SIM screen until the ESC key is pressed.

Note: If the HOLD function is engaged before the Sim Output function is engaged, the simulated output will remain the same even when the ESC key is pressed. Disengage the HOLD function to return to normal output.

Fail Out   This function enables the user to define a specified value that the main current output will go to under fault conditions. When the Relay Option Board is installed, the display will read **Fail Out #1**. When enabled to **ON**, the output may be forced to the current value set in **Fail Val** (next item.) With the Fail Out setting of ON, and a Fail Val setting of 6.5 mA, any alarm condition will cause the current loop output to drop outside the normal operating range to exactly 6.5 mA, indicating a system failure that requires attention.

Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify desired value; selections are **ON**, **OFF**. Press ENTER to store the new value.

Fail Val   Sets the output failure value for Iout#1. When **Fail Out** above is set to **ON, t**his function sets value of the current loop under a FAIL condition. When the Relay Option Board is installed, the display will read **Fail Out #1**. The output may be forced to any current value between 4-20 mA.

Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify desired value; selections are between **4mA**, and **20mA**. Press ENTER to store the new value.

AC POWERED UNITS ONLY

Fail Out #2   This function sets the fail-mode of current loop output #2 under a FAIL condition. The settings and operation are identical to Fail Out for output #1.

Fail Val #2   This function sets the value of current loop output #2 under a FAIL condition. The settings and operation are identical to Fail Out for output #1.

AC POWERED UNITS ONLY

*Failsafe   This function allows the user to set the optional system relays to a failsafe condition. In a failsafe condition, the relay logic is reversed so that the relay is electrically energized in a normal operating state. By doing this, the relay will not only change state when, for example, a H_2O_2 limit is exceeded, but also when power is lost to the controller.

When failsafe is selected to be ON, the normally-open contacts of the relay will be closed during normal operation. In an attempt to make this configuration less confusing, the LCD icon logic is reversed with this setting, and the icon is OFF under this normal condition. Therefore, when the trip condition occurs, the closed N.O. contacts will be opened (relay de-energized), and the LCD icon will illuminate. In addition, a power fail would also cause the same contacts to open.

Set Default   The Set Default function allows the user to return the instrument back to factory default data for all user settings or for just the calibration default. It is intended to be used as a last resort troubleshooting procedure. All user settings or the calibration settings are returned to the original factory values. Hidden factory calibration data remains unchanged. Press ENTER to initiate user entry mode and select either **CAL** or **ALL** with the UP arrow key. The default CAL routine will reset the zero offset to 0.0 nA and reset the slope to 100%.   The default ALL routine will reset all program variables to factory default and should be used with care since it will change any user settings that were programmed in the field.

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Part 7 – Calibration

7.1 Hydrogen Peroxide Calibration

Once power is applied, the sensor must be given time to stabilize. This is best done by following the zeroing procedure below. Establishing a stable zero is critical to the proper operation of the monitor. A complete calibration will include zeroing and spanning the sensor. It is generally unnecessary to set the zero at every calibration, however, it should be done during the initial installation.

7.11 H_2O_2 Zero Cal

Hydrogen peroxide sensors have extremely low offset currents at zero. For this reason, it is normally sufficient to simply leave the zero at the factory default of 0.0 nA. As an alternative, an electronic zero can be set by disconnecting the sensor from the cable and performing steps 1-5 below.

The steps below assume that the sensor has been prepared in accordance with section 5.1, Sensor Assembly, earlier in this manual. Note that the 8 hour waiting time in step 2 below is not required if the monitor has been running for 24 hours prior to zeroing. If the unit has been running with the sensor connected, the sensor will normally return to a stable zero within 15 minutes.

1. Connect the sensor to the electronics by plugging the cable plug into the receptacle on the top of the sensor.

2. Place about an inch of water in a small beaker or other convenient container and immerse the tip of the sensor. The water used need not be distilled, but it must not contain hydrogen peroxide. If the sensor is being used for the first time, allow the sensor to sit undisturbed for at least 4 hours. If the sensor has been in use, 30 –60 minutes is normally enough to establish a good zero.

3. Scroll to the CAL menu section using the MENU key and press ENTER or the UP arrow key. **Cal H_2O_2** will then be displayed.

4. Press the ENTER key. The screen will display a flashing **1-Ref** for span calibration or a **2-Zer** for zero calibration. Using the UP arrow key, set for a **2-Zer** zero calibration and press ENTER. The system now begins acquiring data for the sensor zero calibration value. As data is gathered, the units for sensor current in nanoamps (nA) and temperature may flash. Flashing units indicate that this parameter is unstable. The calibration data point acquisition will stop only when the data remains stable for a pre-determined amount of time. This can be overridden by pressing ENTER. If the data remains unstable for 10 minutes, the calibration will fail and the message **Cal Unstable** will be displayed.

5. If accepted, the screen will display the message **PASS** with the new sensor zero reading (offset), then it will return to the main measurement display. If the calibration fails, a message indicating the cause of the failure will be displayed and the FAIL icon will be turned on. The range of acceptable value for sensor offset is -16nA to +16 nA. Should a FAIL occur, carefully inspect the sensor for a tear in the membrane. It will probably be necessary to rebuild the sensor as described in section 5.4, H_2O_2 Sensor Assembly. Should the offset value remain high and result in calibration failures, review the Service section of this manual, and then contact the service dept. at ATI for further assistance.

The sensor zero offset value in nA from the last zero calibration is displayed on the lower line of the Default Menus for information purposes.

7.12 H_2O_2 Span Cal

Span calibration of the system must be done against a laboratory measurement on the same sample that the sensor is measuring. A sample should be collected from the inlet line feeding the flow cell and quickly analyzed for H_2O_2. When calibrating, it is best to have a reasonably high concentration of H_2O_2 in the system. The higher the value, the smaller will be the calibration errors caused by errors in the laboratory analytical procedure. It is generally preferable to calibrate at values above 2 PPM to reduce calibration errors.

Start flow cell and calibrate system as follows:

1. Place the previously zeroed sensor into the sensor chamber of the flow cell assembly. The sensor is inserted into the side of the flow cell and is sealed in place with a double o-ring. The o-rings are lubricated at the factory to allow the sensor to slide smoothly into place. If insertion becomes difficult, use a small amount of silicon grease to lubricate the o-rings. If the low-volume flow cell is used, screw the sensor into the flow cell until the membrane cap bottoms out on the acrylic flow cell. Do not over-tighten

2. Turn on the inlet water flow to the flow cell and adjust the inlet flow rate so that water is overflowing from the inlet chamber. The best performance will be obtained when some water is always overflowing. This maintains constant flow and pressure on the sensor at all times.

3. Allow the system to operate undisturbed for 30-60 minutes. Assuming the water contains H_2O_2, the display will be reading positive sensor current values. If the system is stable, the value on the display will increase to some PPM value and remain at that level. At that point, calibration can continue.

4. If the sensor is on-line, the user may want to set the output HOLD feature prior to calibration to lock out any output fluctuations.

5. Scroll to the CAL menu section using the MENU key and press ENTER or the UP arrow key. **Cal H$_2$O$_2$** will then be displayed.

6. Press the ENTER key. The screen will display a flashing **1-Ref** for span calibration or a **2-Zer** for zero calibration. Using the UP arrow key, set for a **1-Ref** span calibration and press ENTER.

7. The system now begins acquiring data for the calibration value. As data is gathered, the units for ppm and temperature may flash. Flashing units indicate that this parameter is unstable. The calibration data point acquisition will stop only when the data remains stable for a pre-determined amount of time. This can be overridden by pressing ENTER. If the data remains unstable for 10 minutes, the calibration will fail and the message **Cal Unstable** will be displayed.

8. The screen will display the last measured ppm value and a message will be displayed prompting the user for the lab value. The user must then modify the screen value with the arrow keys and press ENTER. The system then performs the proper checks.

9. If accepted, the screen will display the message **PASS** with the new sensor slope reading, then it will return to the main measurement display. If the calibration fails, a message indicating the cause of the failure will be displayed and the FAIL icon will be turned on. The range of acceptable values for sensor slope is 20% to 250%. It may be necessary to rebuild the sensor as described in section 5.4, H_2O_2 Sensor Assembly. Should the slope value remain out of range and result in calibration failures, review the Service Section of this manual, then contact the service dept. at ATI for further assistance.

The sensor offset value in % from the last span calibration is displayed on the lower line of the Default Menus for information purposes.

7.2   Temperature Calibration

The temperature calibration sequence is essentially a 1-point offset calibration that allows adjustments of approximately ±5 °C.

The sensor temperature may be calibrated on line, or the sensor can be removed from the process and placed into a known solution temperature reference. In any case, it is critical that the sensor be allowed to reach temperature equilibrium with the solution in order to provide the highest accuracy. When moving the sensor between widely different temperature conditions, it may be necessary to allow the sensor to stabilize as much as one hour before the calibration sequence is initiated. If the sensor is on-line, the user may want to set the output HOLD feature prior to calibration to lock out any output fluctuations.

1. Scroll to the CAL menu section using the MENU key and press ENTER or the UP arrow key.

2. Press the UP arrow key until **Cal Temp** is displayed.

3. Press the ENTER key. The message **Place sensor in solution then press ENTER** will be displayed. Move the sensor into the calibration reference (if it hasn't been moved already) and wait for temperature equilibrium to be achieved. Press ENTER to begin the calibration sequence.

4. The calibration data gathering process will begin. The message **Wait** will flash as data is accumulated and analyzed. The **°C** or **°F** symbol may flash periodically if the reading is too unstable.

5. The message **Adjust value - press ENTER** will be displayed, and the right-most digit will begin to flash, indicating that the value can be modified. Using the UP and LEFT arrow keys, modify the value to the known ref solution temperature.   Adjustments up to ± 5 °C from the factory calibrated temperature are allowed. Press ENTER.

Once completed, the display will indicate **PASS** or **FAIL**. If the unit fails, the temperature adjustment may be out of range, the sensor may not have achieved complete temperature equilibrium, or there may be a problem with the temperature element. In the event of calibration failure, it is recommended to attempt the calibration again immediately.

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Part 8 – PID Controller Details

8.1   PID Description

PID control, like many other control schemes, are used in chemical control to improve the efficiency of chemical addition or control. By properly tuning the control loop that controls chemical additon, only the amount of chemical that is truly required is added to the system, saving money.   The savings can be substantial when compared to a system which may be simply adding chemical at a constant rate to maintain some minimal addition under even the worst case conditions. The PID output controller is highly advantageous over simple control schemes that just utilize direct (proportional only) 4-20 mA output connections for control, since the PID controller can automatically adjust the "rate" of recovery based on the error between the setpoint and the measured value – which can be a substantial efficency improvement..

The PID controller is basically designed to provide a "servo"action on the 4-20 mA output to control a process. If the user requires that a measured process stay as close as possible to a specific setpoint value, the controller output will change from 0% to 100% in an effort to keep the process at the setpoint. To effect this control, the controller must be used with properly selected control elements (valves, proper chemicials, etc.) that enable the controller to add or subtract chemical rapidly enough. This is not only specific to pumps and valves, but also to line sizes, delays in the system, etc.

This section is included to give a brief description of tuning details for the PID controller, and is not intended to be an exhaustive analysis of the complexities of PID loop tuning. Numerous sources are available for specialized methods of tuning that are appropriate for a specific application.

8.2   PID Algorithm

As most users of PID controllers realize, the terminology for the actual agorithm terms and even the agorithms themselves can vary between different manufacturers. This is important to recognize as early as possible, since just plugging in similar values from one controller into another can result in dramatically different results. There are various basic forms of PID algorithms that are commonly seen, and the implementation here is the most common version; The ISA algorithm (commonly referred to as the "ideal" algorithm.)

$$output = P\left[e(t) + \frac{1}{I}\int e(t)d(t) + D\frac{de(t)}{dt} \right]$$

Where:

output =	controller output
P =	proportional gain
I =	integral gain
D =	derivative gain
t =	time
e(t) =	controller error (e=measured variable – setpoint)

Figure 21 - ISA (Ideal) PID Equation

The most notable feature of the algorithm is the fact the proportional gain term affects all components directly (unlike some other algorithms - like the "series" form.) If a pre-existing controller utilizes the same form of the algorithm shown above, it is likely similar settings can for made if the units on the settings are exactly the same. Be careful of this, as many times the units are the reciprocals of each other (ie. reps-per-min, sec-per-rep.)

PID stands for "proportional, integral, derivative." These terms describe the three elements of the complete controller action, and each contributes a specific reaction in the control process. The PID controller is designed to be primarily used in a "closed-loop" control scheme, where the output of the controller directly affects the input through some control device, such as a pump, valve, etc.

Although the three components of the PID are described in the setting area (section 6.25), here are more general descriptions of what each of the PID elements contribute to the overall action of the controller.

P   Proportional gain. With no "I" or "D" contribution, the controller output is simply a factor of the proportional gain multiplied by the input error (difference between the measured input and the controller setpoint.) Because a typical chemical control loop cannot react instantaneously to a correction signal, proportional gain is typically not efficient by itself – it must be combined with some integral action to be useful. Set the P term to a number between 2-4 to start. Higher numbers will cause the controller action to be quicker.

I   Integral gain. Integral gain is what allows the controller to eventually drive the input error to zero – providing accuracy to the control loop. It must be used to affect the accuracy in the servo action of the controller. Like proportional gain, increasing integral gain results in the control action happening quicker. Set the I term to a number between 3-5 to start (1-2 more than P). Like proportional gain, increasing the integral term will cause the controller action to be quicker.

D   Derivative gain. The addition of derivative control can be problematic in many applications, because it greatly contributes to oscillatory behavior. In inherently slow chemical control process', differential control is generally added in very small amounts to suppress erratic actions in the process that are non-continuous, such as pumps and valves clicking on and off. However, as a starting point for chemical process control, its best to leave the "D" term set to 0.

Based on these descriptions, the focus on tuning for chemical applications really only involves adjustment of "P" and "I" in most cases. However, increasing both increases the response of the controller. The difference is in the time of recovery. Although combinations of high "P's" and low "I" will appear to operate the same as combinations of low "P's" and high "I's", there will be a difference in rate of recovery and stability. Because of the way the algorithm is structured, large "P's" can have a larger impact to instability, because the proportional gain term impacts all the other terms directly. Therefore, keep proportional gain lower to start and increase integral gain to achieve the effect required.

Many of the classical tuning techniques have the user start with all values at 0, and then increase the P term until oscillations occur. The P value is then reduced to ½ of the oscillatory value, and the I term is increased to give the desired response. This can be done with the Q45H controller, with the exception that the I term should start no lower than 1.0.

If it appears that even large amounts of integral gain (>20) don't appreciably increase the desired response, drop I back to about 1.0, and increase P by 1.00, and start increasing I again. In most chemical control schemes, I will be approximately 3 times the value of P.

8.3   Classical PID Tuning

Unlike many high speed position applications where PID loops are commonly used, the chemical feed application employed by this instrument does not require intense mathematical exercise to determine tuning parmaters for the PID. In fact, the risk of instability is far greater with overly tuned PID control schemes. In addition, many of the classical mathematical exercises can be damaging or wasteful in the use of chemicals when the process is bumped with large aqmounts of input error to seek a response curve. Because of this, the general adjustment guidleines described in section 8.2 are sufficient for almost all application tuning for this instrument. Beyond this, many sources are available for classical tuning methods.

8.4 Manual PID Override Control

The Q45 PID output function allows the user to take manual control of the PID control signal. This is often useful when starting up a control loop, or in the event that you wish to bump the system manually to measure system response time.

To access the manual PID control, you must be in the MEASURE mode of operation and you must have the PID output displayed on the lower line. This line will indicate "XX.X%   XX.X mA" with the X values simply indicating the current values. With this display on the screen, press and hold the ENTER key for about 5 seconds. You will see a small "m" show up between the % value and the mA value. This indicates you are now in manual mode.

Once in manual, you may increase the PID output by pressing the UP arrow or you may decrease the output by pressing the LEFT arrow. This will allow you to drive the PID output to any desired setting.

To revert to normal PID control, press and hold the ENTER key again until the " m" indicator disappears.

8.5   Common PID Pitfalls

The most common problem occurring in PID control applications involves the false belief that proper settings on only the PID controller can balance any process to an efficient level.

Close-loop control can only be effective if all elements in the loop are properly selected for the application, and the process behavior is properly understood. Luckily, the nature of simple chemical control process' are generally slow in nature. Therefore, even a de-tuned controller (one that respponds somewhat slow) can still provide substantial improvements to setpoint control. In fact, damaging oscillatory behavior is far more likley in tightly tuned controllers where the user attempted to increase repsonse too much.

When deciding on a PID control scheme, it is important to initially review all elements of the process. Sticking valves, undersized pumps, or delays in reaction times associated with chemical addtion can have a dramatic effect on the stability of the control loop. When controlling a chemical mix or reaction, the sensor should be placed in a location that ensures proper mixing or reaction time has occurred.

The easiest process' to control with closed-loop schemes are generally linear, and symmetrial, in nature. For example, controlling level in tank where the opening of valve for a fixed period of time correspnds linearly to the amount that flows into a tank. Chemical control process' can be more problematic when the nature of the setpoint value is non-linear relative to the input of chemical added. For example, pH control of a process may appear linear only in a certain range of operation, and become highly exponential at the extreme ranges of the measuring scale. In addtion, if a chemical process is not symmetrical, that means it responds differentally to the addition and subtraction of chemical.   It is important in these applications to study steady-state impact as well as step-change impact to process changes. In other words, once the process has apparently been tuned under normal operating conditions, the user should attempt to force a dramatic change to the input to study how the output reacts. If this is difficult to do with the actual process input (the recommended method), the user can place the control in manual at an extreme control point such as 5% or 95%, and release it in manual. The recovery should not be overly oscillatory. If so, the loop needs to be de-tuned to deal with that condition (reduce P and/or I.)

Part 9 – System Maintenance

9.1 General

The Q45/84 Hydrogen Peroxide System will generally provide unattended operation over long periods of time. With proper care, the system should continue to provide measurements indefinitely. For reliable operation, maintenance on the system must be done on a regular schedule. Keep in mind that preventive maintenance on a regular schedule is much less troublesome than emergency maintenance that always seems to come at the wrong time.

9.2 Analyzer Maintenance

No unusual maintenance of the analyzer is required if installed according to the guidelines of this operating manual. If the enclosure door is frequently opened and closed, it would be wise to periodically inspect the enclosure sealing gasket for breaks or tears.

9.3 Peroxide Sensor Maintenance

Sensor maintenance is required for accurate measurements. The primary requirement is simply to keep the sensor membrane clean. The membrane is a micro-porous polymer that is resistant to anything that will be encountered in water streams. However, deposits can form on the surface or in the pores of the membrane, and these deposits will reduce the sensitivity. Certain constituents in water, mainly iron and manganese, will form precipitates. These precipitates can sometimes form a coating on the membrane.

Because membranes are micro-porous, they can be relatively difficult to clean effectively. Immersing the tip of the sensor in 1N nitric acid solution will sometimes remove deposits that cause low sensitivity, but this is not always the case. The recommended practice is to simply replace the membrane when it becomes fouled. To change a membrane, follow the Sensor Assembly procedure on page 14 of this manual. Do not reuse the electrolyte from the sensor when changing a membrane. Always refill with fresh electrolyte. The electrolyte is stable and does not have a limited shelf life.

Refer again to the explanation of the sensor slope number after an accepted span calibration on the lower MEASURE screen. In normal operation, the slope of the sensor output will decrease over time as the membrane becomes fouled. This reduction indicates that the sensor is loosing sensitivity to H_2O_2. It is good practice to replace the membrane if the slope number falls to 30-40%. The value will not go below 20%.

Even if no buildup is apparent on the membrane, it should be changed on a regular schedule. The recommended membrane change interval is every 3 months. For high purity water applications, this can probably be extended if desired, but a more frequent changing interval is a small price to pay for avoiding membrane failure at the wrong time.

While the sensor is disassembled for membrane changing, examine the condition of the o-rings on both ends of the electrolyte chamber. If the o-rings show any signs of damage, replace them with new ones from the spare parts kit. It is good practice to change these o-rings once a year, regardless of their condition.

9.31   Sensor Acid Cleaning

Over an extended operating period, H_2O_2 sensors can slowly accumulate deposits on the surface of the platinum electrode. Typically, this type of buildup occurs over years of operation, but can sometimes occur more quickly in high levels of manganese, iron, or other metals are dissolved in the water. The platinum electrode can be "acid cleaned" using nitric acid solutions.

> # WARNING
>
> **THIS ACID CLEANING PROCEDURE INVOLVES THE USE OF HIGHLY CORROSIVE ACID SOLUTIONS. IT SHOULD ONLY BE COMPLETED BY TRAINED PERSONNEL USING PROTECTIVE EYEWEAR AND GLOVES. IF THERE IS ANY DOUBT ABOUT YOUR ABILITY TO SAFELY ACCOMPLISH THIS PROCEDURE, RETURN THE SENSOR TO ATI FOR FACTORY CLEANING!**

To acid clean the electrode assembly, remove the electrolyte chamber from the sensor so that the so that both electrodes are exposed. Then follow the procedure below.

1. Place a small amount of 50% nitric acid solution in a beaker. Put in just enough so that the platinum tip of the sensor can be submerged without any contact with the silver coil.

2. Allow the sensor to soak in this acid solution for 2 minutes. Remove the sensor body and rinse the platinum tip thoroughly with distilled water. Discard the nitric acid safely and according to all environmental regulations.

3. Fill the beaker with distilled water to the level sufficient to submerge both the tip and the silver coil. Do not allow the connector at the back of the sensor to be submerged. Allow the electrodes to soak in distilled water for 30 minutes.

4. Put a new membrane and fresh electrolyte in the electrolyte chamber and reassemble the sensor. Connect to the H_2O_2 monitor electronics and allow the sensor to stabilize for at least 2-4 hours. The sensor can be placed in the flow cell with ozonated water running through it during stabilization. However, the readings will not be useful for 24 hours.

9.4   Flow Cell Maintenance

The maintenance on the flow cell is simple cleaning. The flow cell is clear to make examination of the condition of the sensor easier without interfering with operations.   The flow cell may be cleaned by wiping or by washing with detergents or dilute acids. Do not try to clean with solvents as the acrylic may craze or crack.

Change the o-ring in the flow cell yearly or if any damage is observed.   If insertion of the sensor into the flow cell becomes difficult, use silicon grease to lubricate the o-rings that hold the sensor in place. Use only enough grease to provide surface lubrication. Excess grease could foul the sensor membrane.

Part 10 – Troubleshooting

10.1 General

The information included in this section is intended to be used in an attempt to quickly resolve an operational problem with the system. During any troubleshooting process, it will save the most time if the operator can first determine if the problem is related to the analyzer, sensor, or some external source. Therefore, this section is organized from the approach of excluding any likely external sources, isolating the analyzer, and finally isolating the sensor. If these procedures still do not resolve the operational problems, any results the operator may have noted here will be very helpful when discussing the problem with the factory technical support group.

10.2 External Sources of Problems

To begin this process, review the connections of the system to all external connections.

1. Verify the analyzer is earth grounded. For all configurations of the analyzer, an earth ground connection MUST be present for the shielding systems in the electronics to be active. Grounded conduit provides no earth connection to the plastic enclosure, so an earth ground wiring connection must be made at the power input terminal strip. Verify metal shield is present over incoming power connections. This shield is for safety purposes, but also blocks electrical spikes from relay and power wiring.

2. Verify the proper power input is present (115/230/16-35Vdc).

3. Verify the loads on any 4-20 mA outputs do not exceed the limits in the Instrument Specifications. During troubleshooting, it is many times helpful to disconnect all these outputs and place wire-shorts across the terminals in the instrument to isolate the system and evaluate any problems which may be coming down the analog output connections.

4. Do not run sensor cables or analog output wiring in the same conduits as power wiring. If low voltage signal cables must come near power wiring, cross them at 90° to minimize coupling.

5. If rigid conduit has been run directly to the Q45 enclosure, check for signs that moisture has followed conduit into the enclosure.

6. Check for ground loops. Although the membrane sensor is electrically isolated from the process water, high frequency sources of electrical noise may still cause erratic behavior in extreme conditions. If readings are very erratic after wiring has been checked, check for a possible AC ground loop by temporarily disconnecting feed and drain lines from the flow cell while there is still water on the inside. The reading should be initially stable and then fall very slowly in a smooth fashion as peroxide is depleted in the static sample.

7. On relay based systems, check the load that is connected to the relay contacts. Verify the load is within the contact rating of the relays. Relay contacts which have been used for higher power AC current loads may become unsuitable for very low signal DC loads later on because a small amount of pitting can form on the contacts. If the load is highly inductive (solenoids, motor starters, large aux relays), note that the contact rating will be de-rated to a lower level. Also, due to the large amount of energy present in circuits driving these types of loads when they are switched on an off, the relay wiring placement can result in electrical interference for other devices. This can be quickly resolved by moving wiring, or by adding very inexpensive snubbers (such As Quencharcs) to the load.

8. Carefully examine any junction box connections for loose wiring or bad wire stripping. If possible, connect the sensor directly to the analyzer for testing.

9. Check sensor membrane for fouling. Look closely for signs of grease or oil which may be present. Replace membrane and electrolyte, allow to stabilize, and re-check. The procedure in H_2O_2 Sensor Assembly, on page 36, must be followed when replacing the membrane.

10.3   Analyzer Tests

1. Disconnect power and completely disconnect all output wiring coming from the analyzer. Remove sensor wiring, relay wiring, and analog output wiring. Re-apply power to the analyzer.

2. Using the Simulate feature, check analog outputs and relays with a DVM.

3. Check cell drive circuit. Place a wire short between terminals WHITE and BLUE. With a digital voltmeter (DVM), measure the voltage between terminals ORANGE and BLUE on the back of the monitor to verify that the millivolt value is actually -400 mV.

4. Check TC drive circuit. Place a wire-short between the GREEN and BLACK terminals. With a DVM, measure the voltage between terminals BLACK and RED to verify the TC drive voltage of about 4.8-5.1 Vdc open circuit. Remove DVM completely and connect a 100 Ohm resistor from the BLACK to RED

terminals. The temperature reading should display approximately 0°C and the H_2O_2 reading should display approximately 0 ppm.

10.4 Display Messages

The Q45 Series instruments provide a number of diagnostic messages which indicate problems during normal operation and calibration. These messages appear as prompts on the secondary line of the display or as items on the Fault List.

MESSAGE	DESCRIPTION	POSSIBLE CORRECTION
Max is 200	Entry failed, maximum user value allowed is 200.	Reduce value to ≤ 200
Min is 200	Entry failed, minimum value allowed is 20.	Increase value to ≥ 20
Cal Unstable	Calibration problem, data too unstable to calibrate. Icons will not stop flashing if data is too unstable. User can bypass by pressing ENTER.	Clean sensor, get fresh cal solutions, allow temperature and conductivity readings to fully stabilize, do not handle sensor or cable during calibration.
Out of Range	Input value is outside selected range of the specific list item being configured.	Check manual for limits of the function to be configured.
Locked!	Transmitter security setting is locked.	Enter security code to allow modifications to settings.
Unlocked!	Transmitter security has just been unlocked.	Displayed just after security code has been entered.
Offset High	The sensor zero offset point is out of the acceptable range of –100 to +100 nA.	Check wiring connections to sensor. Allow sensor to operate powered a minimum of 12 hours prior to first zero cal.
Sensor High	The raw signal from the sensor is too high and out of instrument range.	Check wiring connections to sensor.
Sensor Low	The raw signal from the sensor is too low.	Check wiring connections to sensor.
H_2O_2 High	The peroxide reading is greater than the maximum of the User-selected range.	The peroxide reading is over operating limits. Set measuring range to the next highest level.
Temp High	The temperature reading is > 55ºC.	The temperature reading is over operating limits. Check wiring and expected temp level. Perform RTD test as described in sensor manual. Recalibrate sensor temperature element if necessary.
Temp Low	The temperature reading is < -10 ºC	Same as "Temp High" above.
TC Error	TC may be open or shorted.	Check sensor wiring and perform RTD test as described in sensor manual. Check j-box connections.

Figure 22 - Display Messages

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MESSAGE	DESCRIPTION	POSSIBLE CORRECTION
H$_2$O$_2$ Cal Fail	Failure of **H$_2$O$_2$** calibration. FAIL icon will not extinguish until successful calibration has been performed, or 30 minutes passes with no keys being pressed.	Clean sensor redo zero and span calibration. If still failure, sensor slope may be less than 25% or greater than 500%. Perform sensor tests as described in section ?. Replace sensor if still failure.
TC Cal Fail	Failure of temperature calibration. FAIL icon will not extinguish until successful calibration has been performed, or 30 minutes passes with no keys being pressed.	Clean sensor, check cal solution temperature and repeat sensor temp calibration. TC calibration function only allows adjustments of +/- 6 ºC. If still failure, perform sensor tests as described in section ?. Replace sensor if still failure. .
EPROM Fail	Internal nonvolatile memory failure	System failure, consult factory.
Chcksum Fail	Internal software storage error.	System failure, consult factory.
Display Fail	Internal display driver fail.	System failure, consult factory.
Range Cal Fail	Failure of factory temperature calibration.	Consult factory.

10.5   Sensor Tests

1. Check the membrane condition. A membrane that is not stretched smoothly across the tip of the sensor will cause unstable measurements. If necessary, change membrane and electrolyte.

2. Residual H_2O_2 sensors can be tested with a digital voltmeter (DVM) to determine if a major sensor problem exists. Follow the steps below to verify sensor integrity:

    A. Disconnect the six sensor wires from the back of the H_2O_2 monitor. Those wires are color coded white, brown, red, black, and green. Note that the brown wire may be replaced with an orange wire in some cables.

    B. Remove the electrolyte chamber from the sensor and dry the electrodes with a paper towel.

    C. Connect a DVM between the white and orange wires. Reading resistance, you should find an open circuit value of infinite resistance. Repeat this test between white and blue wires. There must be no measurable resistance at all between these wires. Any resistance at all indicates either water in the cable connector or the breakdown in an electrode seal.

    D. Connect a DVM between the red and white wires. The red wire is part of the RTD circuit and the white wire is part of the measuring cell. There should be no connection. Reading resistance, you should find an open circuit value of infinite resistance. Any resistance at all indicates either water in the cable connector or the breakdown in an electrode seal.

    E. Connect the DVM between the red and black wires. These are the RTD leads, and you should find a resistance value that depends on the temperature. The table below lists the resistance values for various temperatures. Reading resistance between the red and green wires should give exactly the same values as between red and black.

Temperature °C	Resistance Ω
0	100.0
5	101.9
10	103.9
15	105.8
20	107.8
25	109.7
30	111.7
35	113.6
40	115.5
45	117.5
50	119.4

Figure 23 - Pt100 RTD Table

If you suspect that water has gotten into a cable connection on a flow type sensor or into the plug connection of a submersible sensor, disconnect the cable and allow the parts of the sensor to sit in a warm place for 24 hours. If water in the connector is the problem, it should dry out sufficiently to allow normal sensor operation. However, steps 4 and 5 above will have to be repeated after drying to see if the problem is gone.

3. Acid clean the sensor electrodes in accordance with the procedure on the previous page.

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Spare Parts

Part No.	Description
07-0183	Q45-84 Dissolved H2O2 2-Wire monitor electronics assy
07-0184	Q45-84 Dissolved H2O2, 115VAC w/Rlys monitor electronics assy
07-0185	Q45-84 Dissolved H2O2, 230VAC w/Rlys monitor electronics assy
00-0725	Dissolved H2O2 sensor, flow type
02-0067	Sensing element body, (for #00-0725)
03-0029	Sensor interconnect cable with connector, 25 ft.
45-0007	Electrolyte chamber
45-0321	Membrane holder, PVC
05-0027	Membranes, pkg. of 10
05-0004*	Spare Parts Kit, screw & o-ring
09-0023	Electrolyte, 4 oz (120 cc)
00-0043	Constant-Head Flowcell assembly with mounting plate
00-1522	Sealed Acrylic Flowcell with mounting plate
42-0014	Flowcell o-ring (each)
07-0100	Junction box
31-0038	Interconnect cable for junction box to monitor wiring
23-0018	Fuse, 100 mA , 250V (115VAC Version)
23-0019	Fuse, 50 mA, 250V (230VAC Version)
23-0022	Fuse, 250 mA, 250V (12-24 VDC)
38-0063	Terminal block plug, 2 position (outputs)
38-0064	Terminal block plug, 6 position (relays)
38-0065	Terminal block plug, 3 position (power)
31-0173	Ribbon cable assembly for AC units
05-0110	Sealed Flowcell Vacuum Breaker

Note: Instrument is supplied with sufficient spare parts for 6-12 months of operation. For 2 year spare parts inventory, 3 each of the items marked with an asterisk are required.

Lock/Unlock Code: 1456